

Segment Anything Model and its applications

Never Stand Still Faculty

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Foundation models

Foundation model refers to any model that is trained on broad data and can be adapted to a wide range of downstream tasks [1].

Foundation models in NLP are very popular (e.g., GPT)...with strong zero-shot and few-shot generalization.

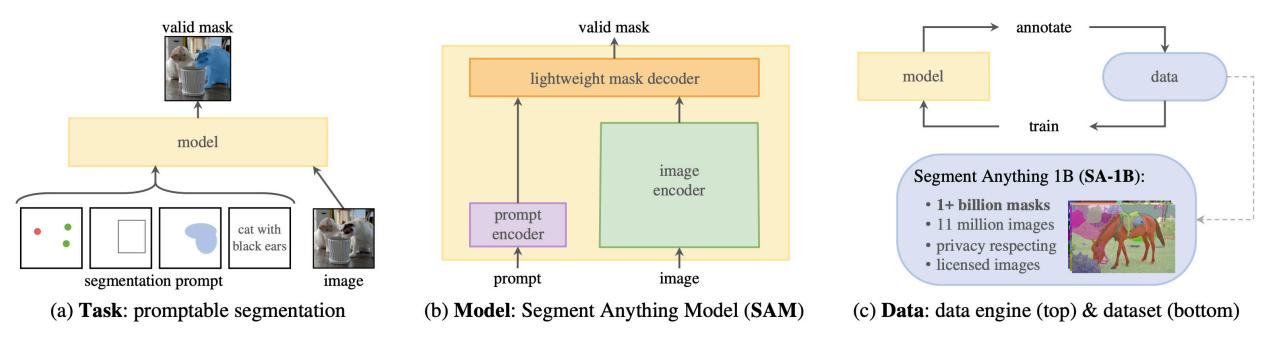
- Pre-trained on web-scale datasets
- Solving diverse tasks via prompt engineering

[1] Bommasani, Rishi, et al. "On the opportunities and risks of foundation models." arXiv preprint arXiv:2108.07258 (2021).



Foundation model for segmentation

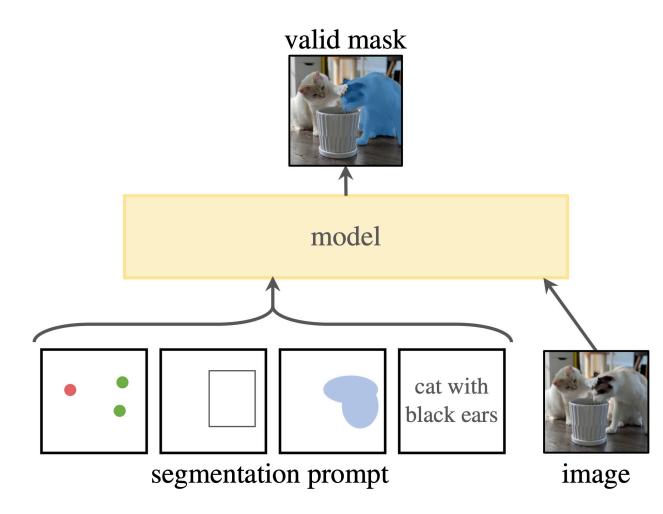
Three keys to the success: Task; Model; Data.



Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Promptable segmentation



A prompt can be:

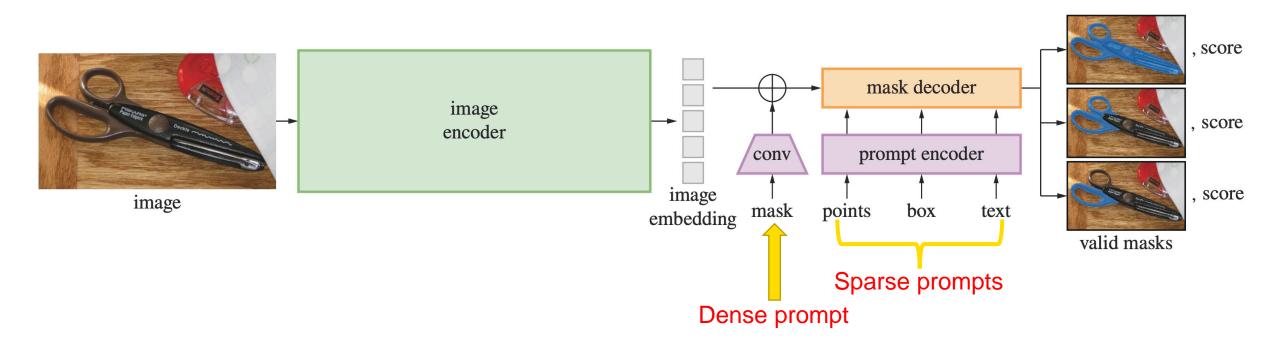
- 1. a set of foreground/background points
- 2. A rough box or mask
- 3. Free-form text
- any information to indicate what to segment

This task aims to return a *valid* segmentation mask given *any prompt*.

Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



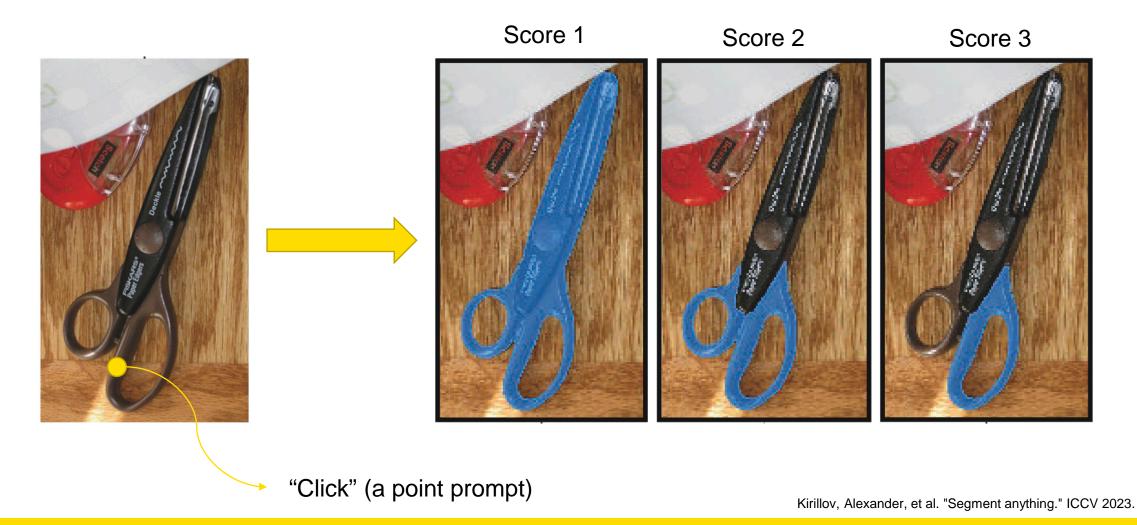
The Overview of SAM



Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Resolving Ambiguity



Efficient & Flexible Model Design

Image encoder:

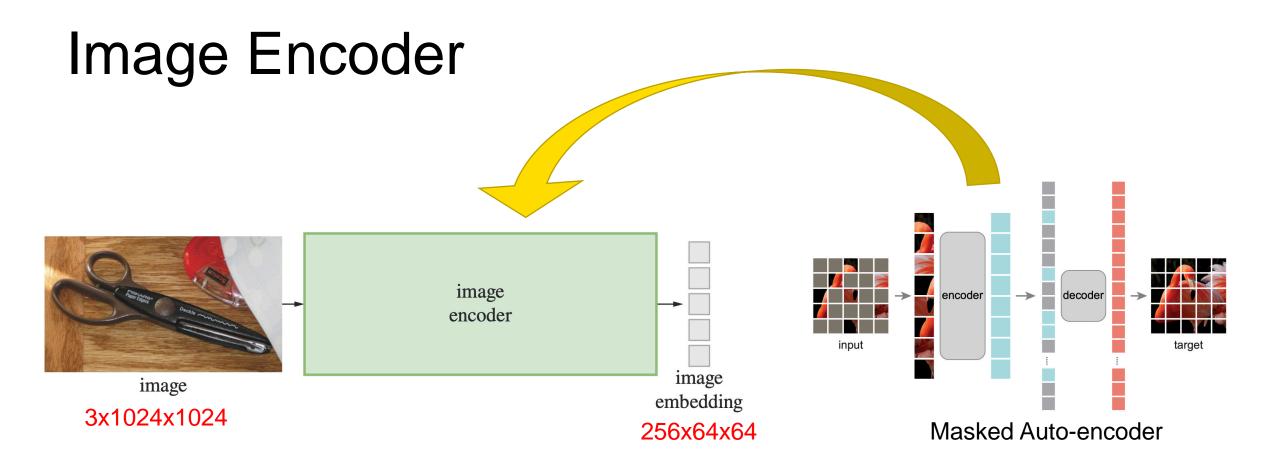
- Runs once per image
- A large ViT model
- Runs on a GPU

Prompt encoder & Mask decoder:

- Runs on each input prompt
- A Lightweight model
- Runs on a web-browser



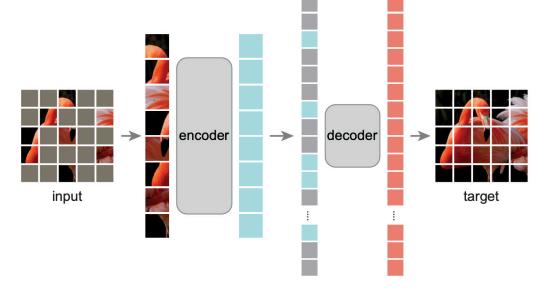
Video from https://segment-anything.com/



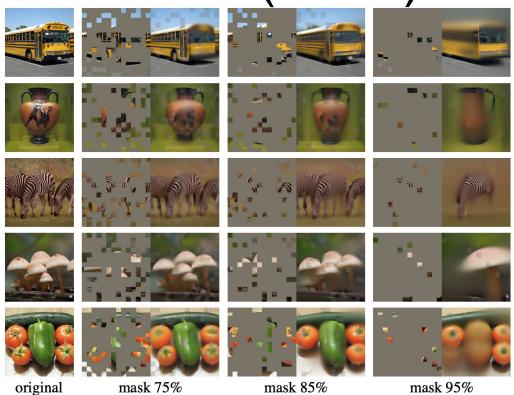
Kirillov, Alexander, et al. "Segment anything." ICCV 2023. He, Kaiming, et al. "Masked autoencoders are scalable vision learners." CVPR 2022.



(Optional) Masked Auto-Encoder (MAE)



MAE architecture. During pre-training, a large random subset of image patches (*e.g.*, 75%) is masked out. The encoder is applied to the small subset of *visible patches*. Mask tokens are introduced *after* the encoder, and the full set of encoded patches and mask tokens is processed by a small decoder that reconstructs the original image in pixels. After pre-training, the decoder is discarded and the encoder is applied to uncorrupted images (full sets of patches) for recognition tasks.

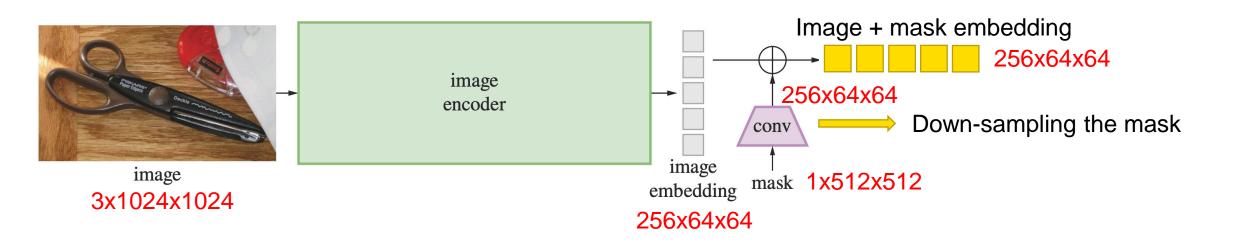


Reconstructions of ImageNet *validation* images using an MAE pre-trained with a masking ratio of 75% but applied on inputs with higher masking ratios. The predictions differ plausibly from the original images, showing that the method can generalize.

He, Kaiming, et al. "Masked autoencoders are scalable vision learners." CVPR 2022.



Dense (Mask) Prompt Encoding



Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Sparse Prompt Encoding

Encoding points

- A positional encoding (PE) of the point's location (x, y)
- A learned embedding indicating "foreground/background" point

Encoding bounding boxes

- The PE for the "top-left" point + a learned embedding indicating "top-left"
- The PE for the "bottom-right" point + a learned embedding indicating "bottom-right"

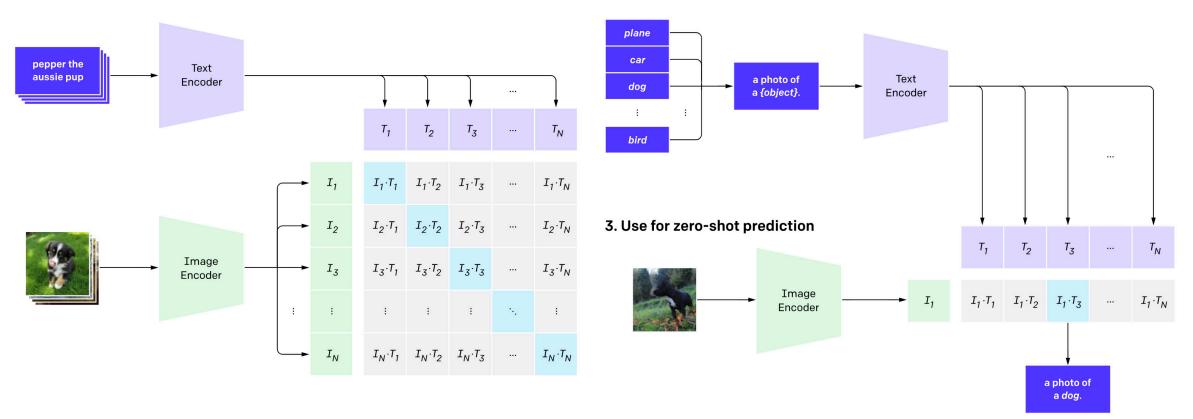
Encoding text prompts

• Text embeddings form the pre-trained CLIP text encoder



(Optional) CLIP

1. Contrastive pre-training

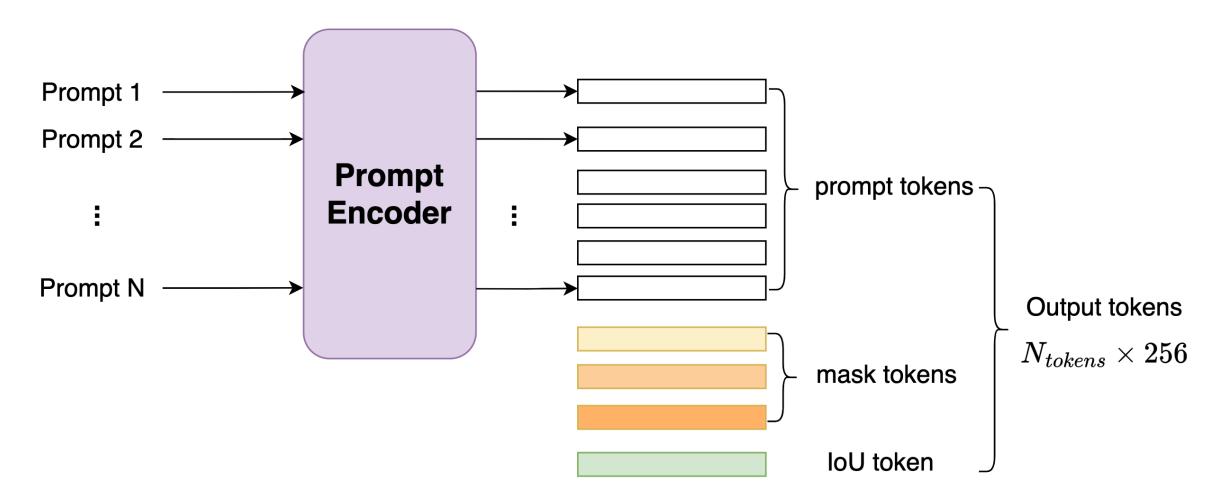


2. Create dataset classifier from label text

Image from https://openai.com/research/clip

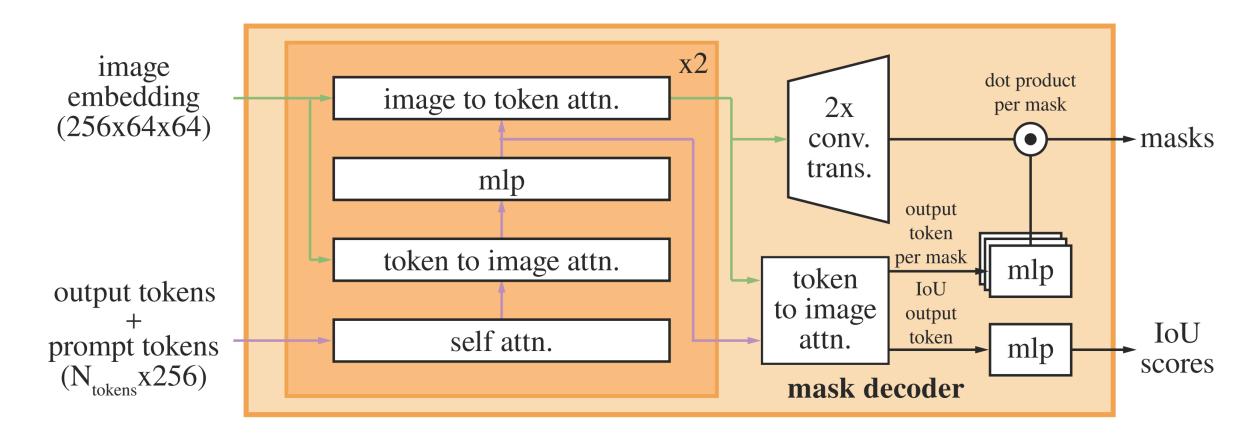


Total prompt encoding





Mask decoder



Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Mask decoder – 3 types of attention

Self-attention of the tokens x2 image Update each prompt/out embedding with contextual embedding image to token attn. (256x64x64)knowledge of other tokens mlp • Cross-attention: tokens \rightarrow image embedding Update the tokens with image context token to image attn. output tokens • Cross-attention: image embedding \rightarrow tokens self attn. prompt tokens $(N_{tokens} x256)$ Update the image embedding with prompt information

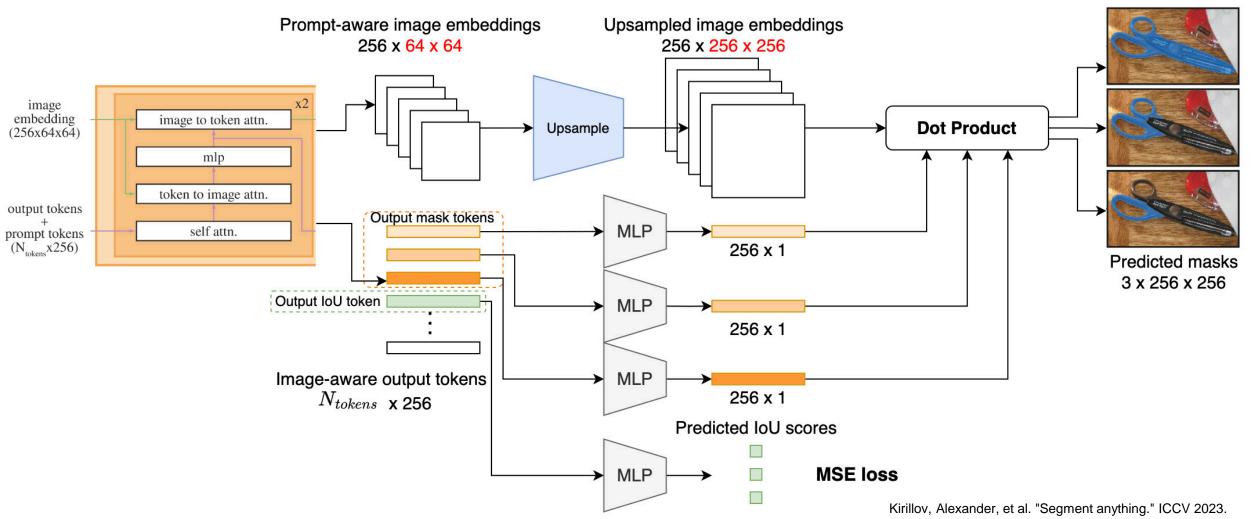
Output tokens: 1. mask tokens; 2. loU token $N_{tokens} = N_{output_mask} + 1 + N_{prompts}$ Here, $N_{output_mask} = 3$ (whole, part, sub-part)

Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Mask decoder

Focal Loss + Dice Loss





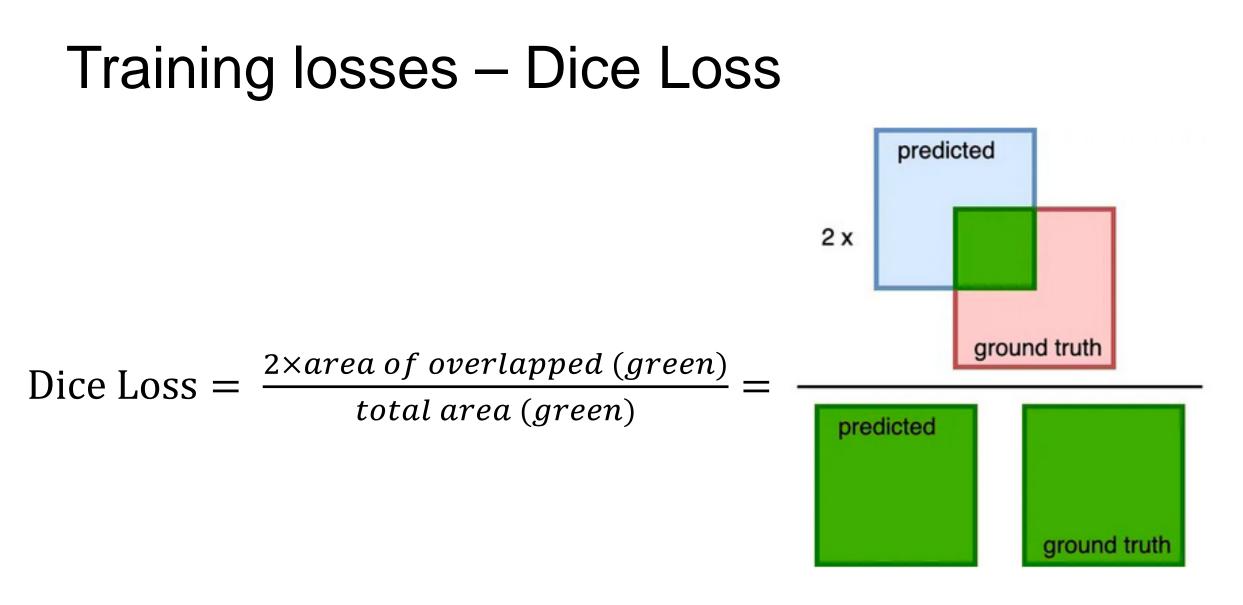
Training losses – Focal Loss

Focal Loss modifies the Cross-Entropy Loss by focusing learning on hard mis-classified examples and down-weighting easy samples.

Focal Loss =
$$-(1 - p_t)^{\gamma} \log(p_t)$$

Lin, Tsung-Yi, et al. "Focal loss for dense object detection." ICCV 2017.





Milletari, Fausto, Nassir Navab, and Seyed-Ahmad Ahmadi. "V-net: Fully convolutional neural networks for volumetric medical image segmentation." 3DV 2016.



Training Algorithm

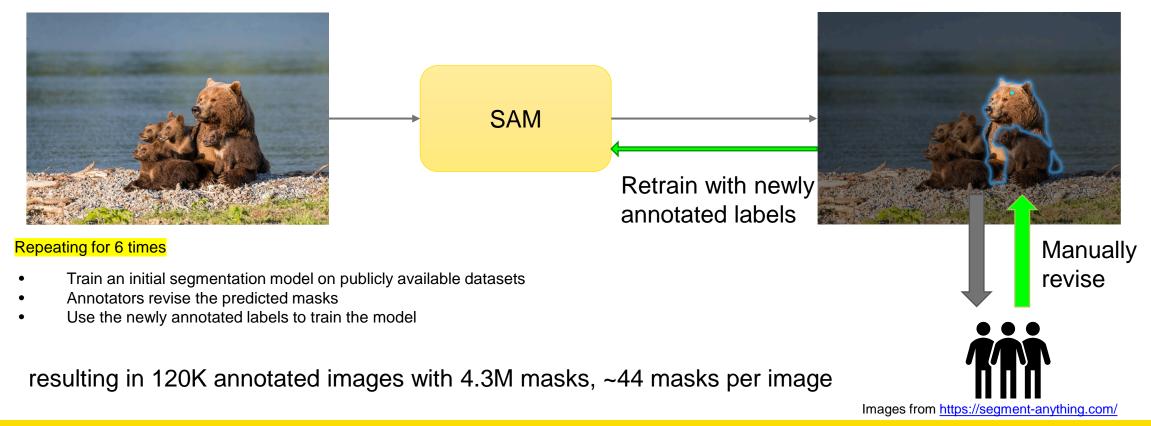
An iterative and interactive segmentation setup:

- 3 stages with different prompts in a total of 11 iterations:
- First iteration: randomly select a point or a box as prompt
- 2-9 iterations: the predicted mask with the highest predicted IoU and a point sampled from the error prediction of that mask
- 10-11 iterations: the predicted mask with the highest predicted IoU



SAM Training with Data Engine

Stage 1 – Assisted-Manual





SAM Training with Data Engine

Stage 2 – Semi-Automatic: To improve the diversity of masks

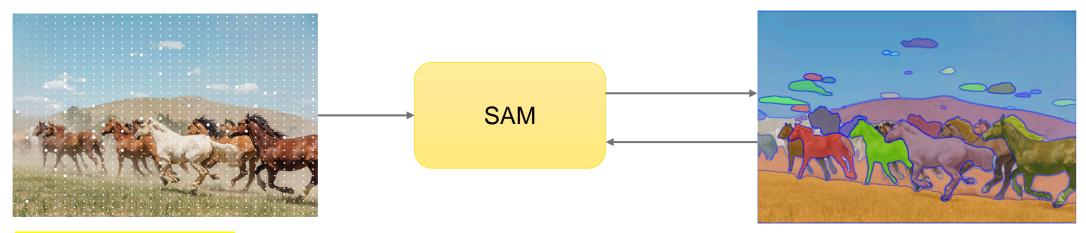


Images from https://segment-anything.com/



SAM Training with Data Engine

Stage 3 – Fully automatic



Prompt with 32 x 32 grid points

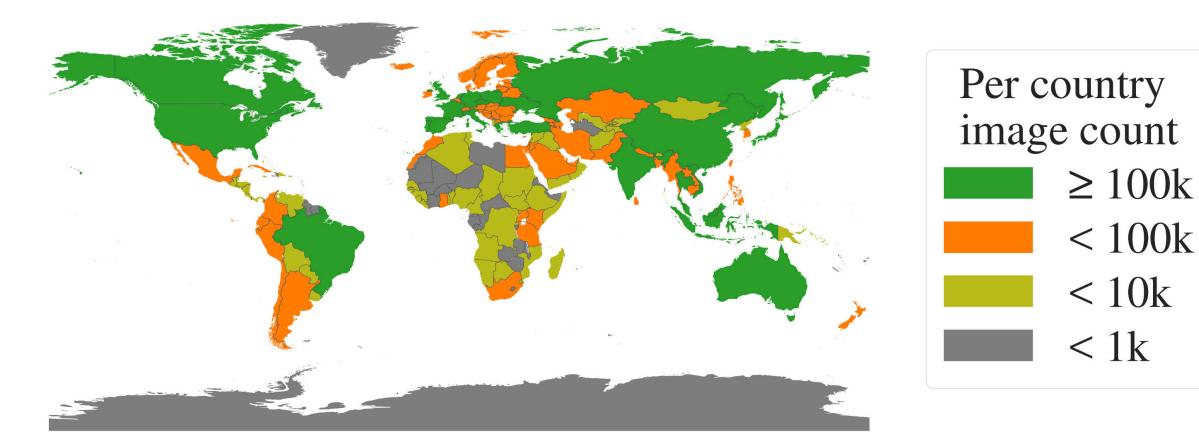
Train SAM on the collected data so far (300 K images with 10.2 M masks) Predict 3 outputs, i.e., whole, part, and subpart.

Resulting in the SA-1B dataset consisting of 11M *high-resolution* images (3300x4950) with *automatically generated* 1.1B masks

Images from https://segment-anything.com/



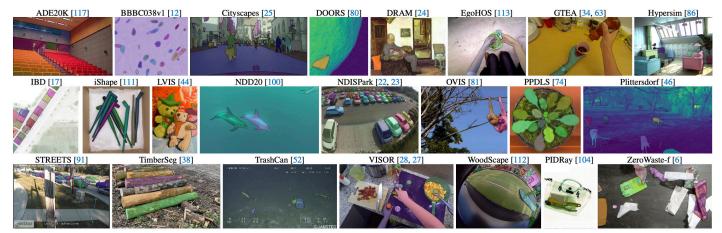
SA-1B Dataset -- Geographic Distribution



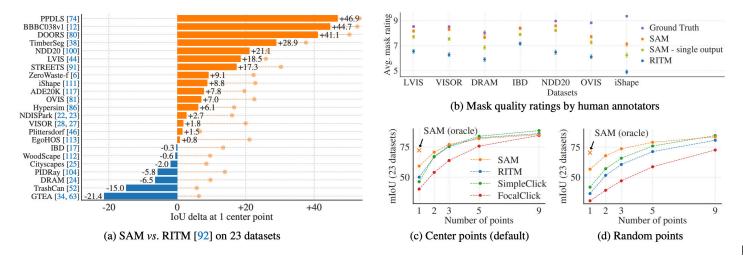
Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Zero-shot Single Point Valid Mask Evaluation



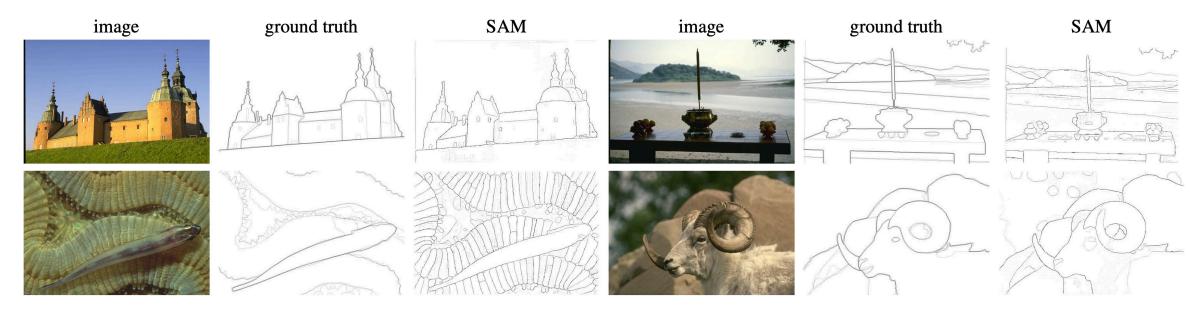
Samples from the 23 diverse segmentation datasets used to evaluate SAM's zero-shot transfer capabilities.



Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Zero-shot edge detection

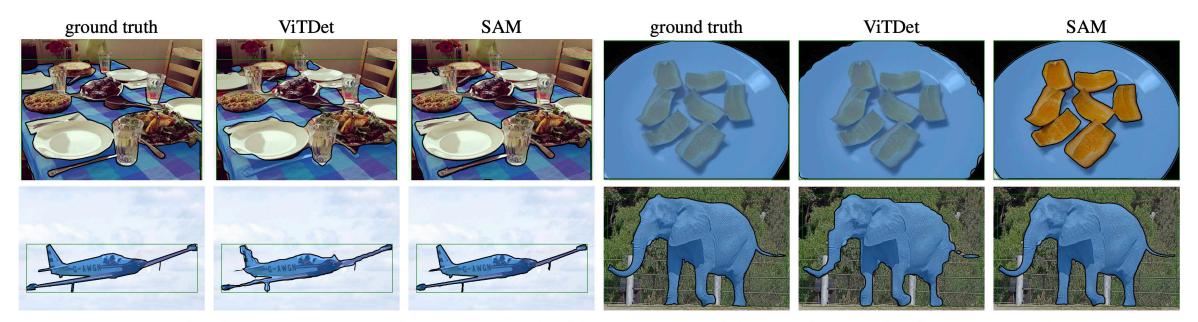


Additional visualizations of zero-shot edge predictions on BSDS500. Recall that SAM was not trained to predict edge maps and did not have access to BSDS images and annotations during training.

Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Zero-shot Instance Segmentation



Zero-shot instance segmentation on LVIS v1. SAM produces higher quality masks than ViTDet. As a zero-shot model, SAM does not have the opportunity to learn specific training data biases; see top-right as an example where SAM makes a modal prediction, whereas the ground truth in LVIS is amodal given that mask annotations in LVIS have no holes.

Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Zero-shot Text-to-Mask



Zero-shot text-to-mask. SAM can work with simple and nuanced text prompts. When SAM fails to make a correct prediction, an additional point prompt can help.

Kirillov, Alexander, et al. "Segment anything." ICCV 2023.



Grounded-SAM: Grounded DINO + SAM

Grounded DINO: Detect anything with text prompt Grounded SAM: Detect and segment anything with text prompt



Images from https://github.com/IDEA-Research/Grounded-Segment-Anything



The running dog

Horse. Clouds. Grasses. Sky. Hill

Grounded-SAM + Stable-Diffusion Inpainting

Generating new data!



Text Prompt: Bench



Grounded-SAM Output



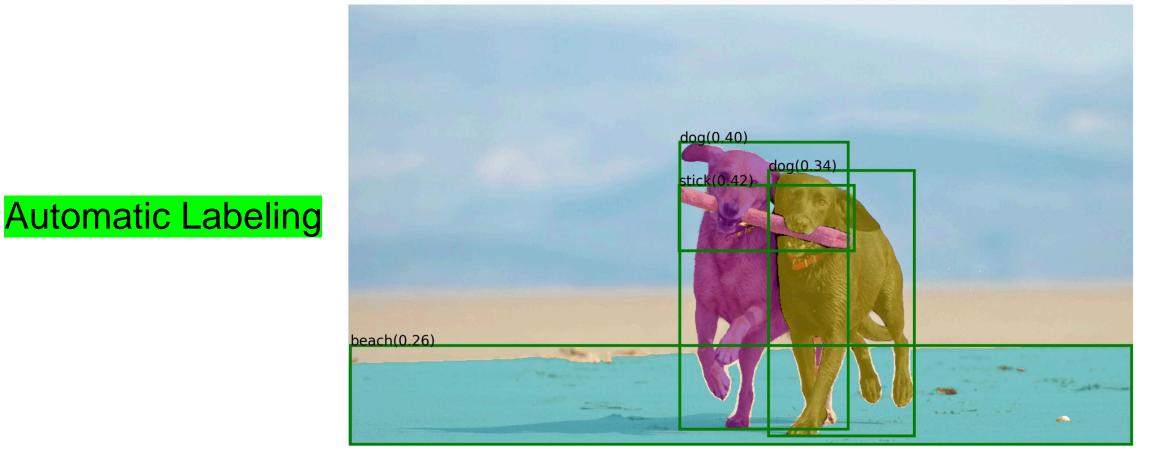
Stable-Diffusion Inpainting A Sofa, high quality, detailed

Images from https://github.com/IDEA-Research/Grounded-Segment-Anything



BLIP + Grounded-SAM

there are two dogs playing with a stick on the beach



Images from https://github.com/IDEA-Research/Grounded-Segment-Anything



Grounded-SAM + Whisper

Detect anything with text prompt with speech



"Change the dog to a monkey"









Images from https://github.com/IDEA-Research/Grounded-Segment-Anything



Conclusion

SAM

- defines a generalized segmentation approach: *promptable segmentation*
- builds a model that supports flexible prompting and real-time inference
- build a data engine that acquired the largest ever segmentation dataset SA-1B





Questions?