

COMP9517: Computer Vision

Motion Tracking Applications in Biomedical Computer Vision

Topics

- Example of change detection
 - Patient motion correction in angiography
- Examples of template matching
 - Cell motion correction in microscopy
 - Monomodal brain image registration
 - Multimodal medical image registration
- Example of optical flow
 - Heart tissue motion estimation
- Examples of object tracking
 - Particle tracking in molecular biology
 - Bayesian multitarget tracking method
 - Heart motion tracking and analysis
 - Tracking for neuron reconstruction
 - Object tracking in cell biology

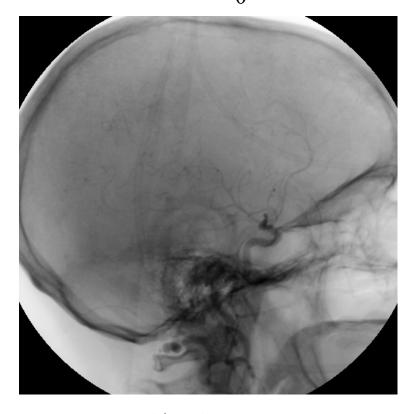
Example of Change Detection

Digital Subtraction Angiography

X-ray at time t_0

Mask Image

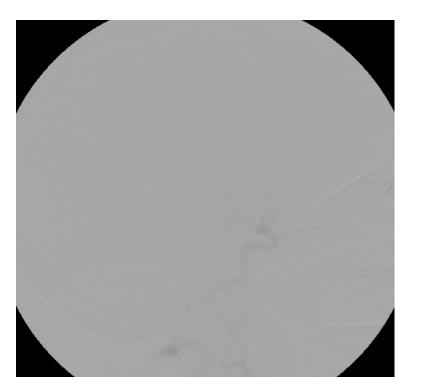
X-ray at time $t_0 + \Delta t$



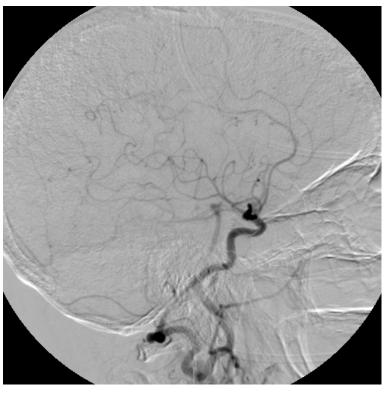
Live Image

Digital Subtraction Angiography

Live – Mask



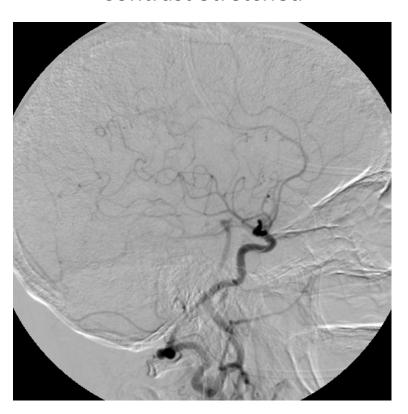
Contrast Stretched



Meijering et al., Radiology, 2001

Digital Subtraction Angiography

Contrast Stretched



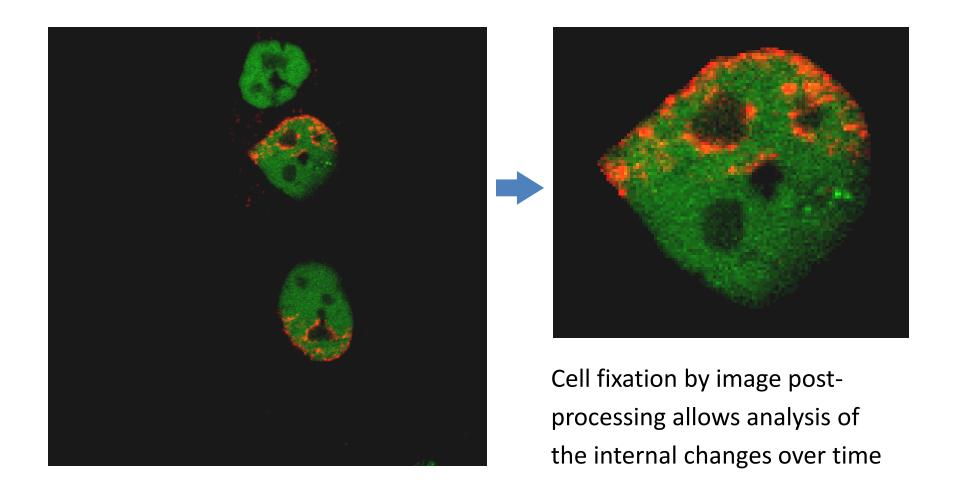
Motion Corrected



Automatic motion correction here is a form of template matching

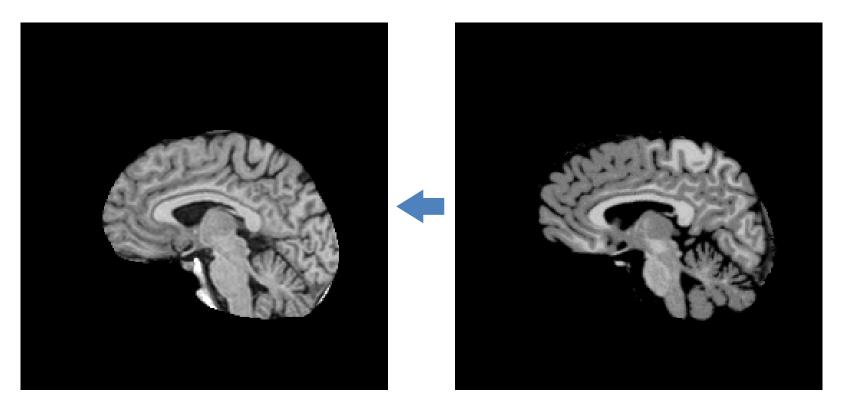
Examples of Template Matching

Cell Motion Correction

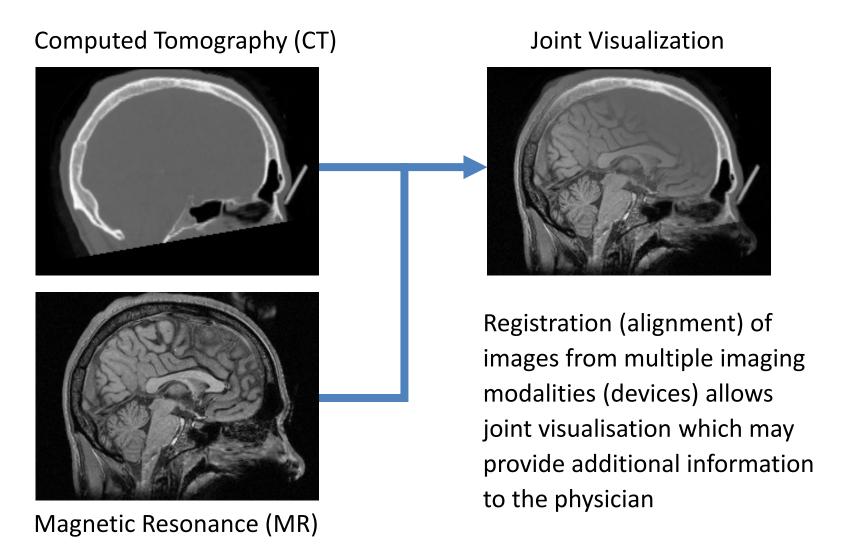


Brain Image Registration

To understand how the human brain develops from childhood to adulthood and to study developmental disorders we can use magnetic resonance imaging (MRI) at different ages and match the images to a template using automatic image registration techniques

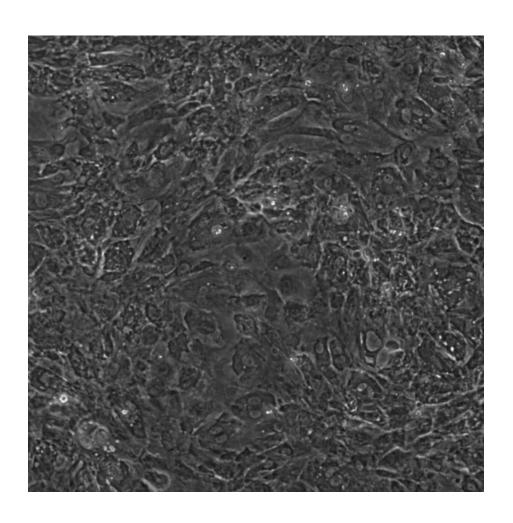


Multimodal Image Registration



Example of Optical Flow

Heart Tissue Motion Estimation



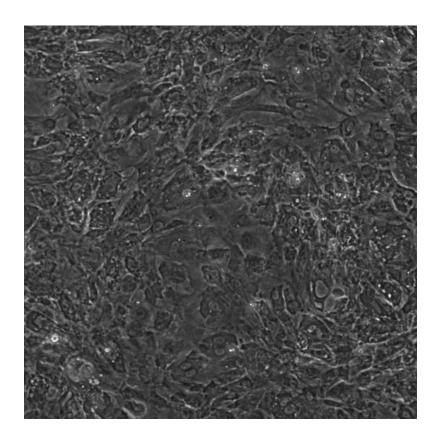
- Heart tissue cultured 6 days
- Mono-layer cardiomyocytes
- Phase-contrast microscopy
- Real-time imaging 24 fps

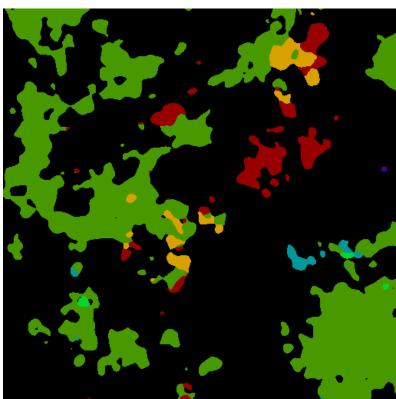
Since the images contain rich information it is easy to estimate local gradients with high accuracy so this is a perfect case for the optical flow method

$$\nabla f \cdot v = -f_t$$

Heart Tissue Motion



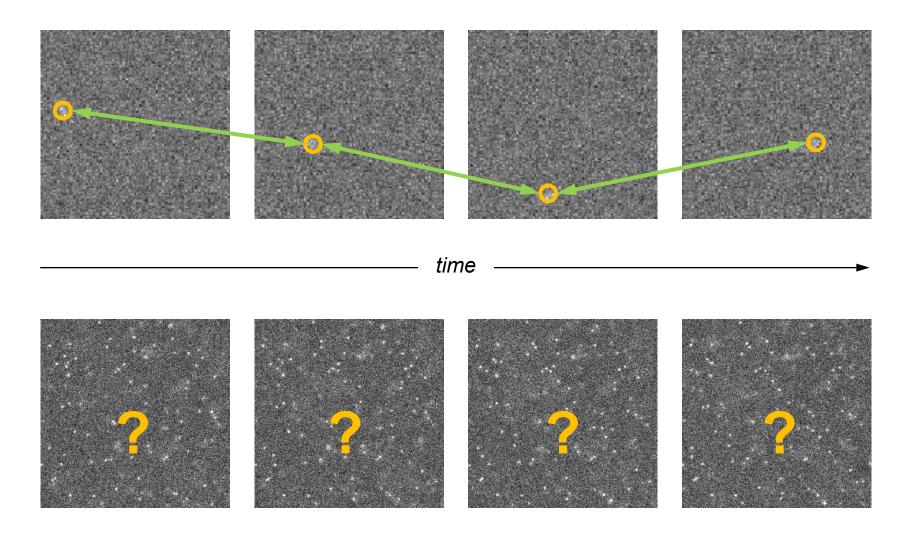




Motion vectors visualised by direction (color) and magnitude (intensity)

Examples of Object Tracking

Particle Tracking Problem



Bayesian Tracking

Computing the degree of belief in the object state by taking into account all available evidence up to the current time point

- State: $X_t = (r_t, v_t, a_t, s_t, I_t, \ldots)$ expressed as probability density $P(X_t)$ Position, velocity, acceleration, shape, intensity, ...
- Evidence: a set of images or extracted features $Y_t = \{y_0, \dots, y_t\}$

Prior Transition Model Posterior
$$P(X_t|Y_{t-1}) = \int D(X_t|X_{t-1}) P(X_{t-1}|Y_{t-1}) dX_{t-1}$$

• Correction:
$$P(X_t|Y_t) \propto L(Y_t|X_t) P(X_t|Y_{t-1})$$
Posterior Observation Model Prior

Bayesian Multitarget Tracking

Extend the state space to include the states of all targets

$$X_{t} = (X_{1;t}, X_{2;t}, \dots, X_{N;t})$$

$$X_{1;t} = (r_{1;t}, v_{1;t}, a_{1;t}, s_{1;t}, I_{1;t}, \dots)$$

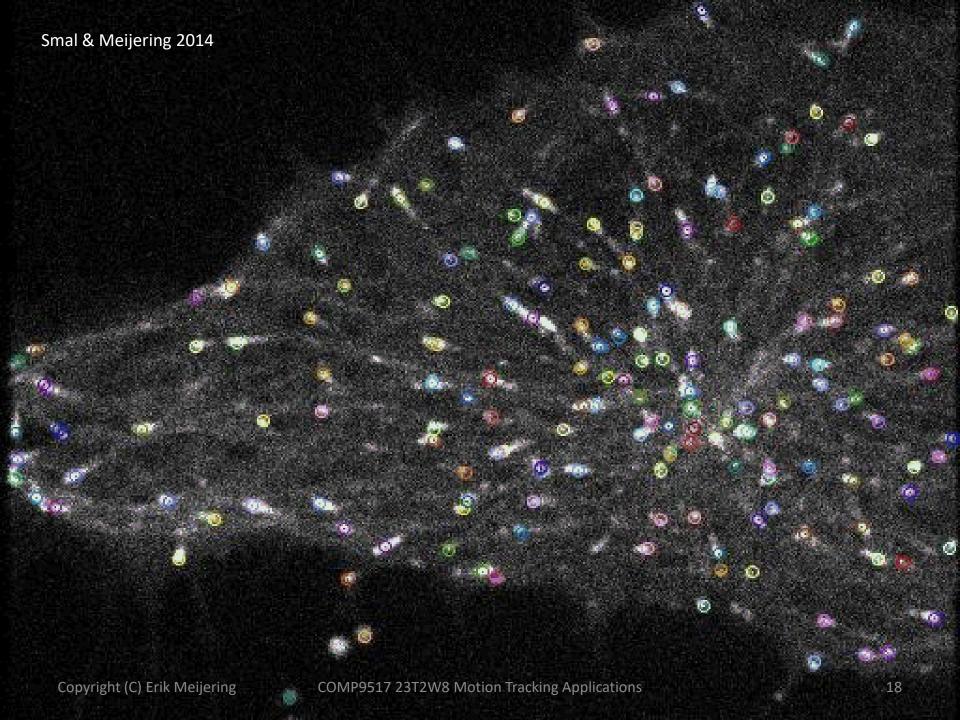
$$X_{N;t} = (r_{N;t}, v_{N;t}, a_{N;t}, s_{N;t}, I_{N;t}, \dots)$$

Computational cost grows exponentially with the number of targets

Use a mixture model of single-target probability densities

$$P(X_t|Y_t) = \sum_{n=1}^{N} w_{n;t} P_n(X_t|Y_t)$$

Requires heuristics to keep track of number of targets and identities



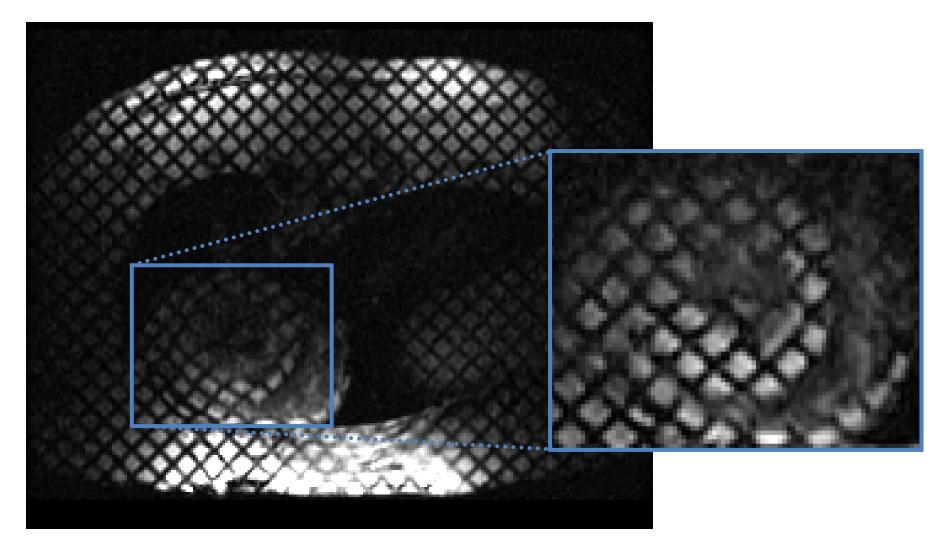
Objective comparison of particle tracking methods

Nicolas Chenouard^{1-3,25}, Ihor Smal^{4,5,25}, Fabrice de Chaumont^{1,25}, Martin Maška^{6,7,25}, Ivo F Sbalzarini⁸, Yuanhao Gong⁸, Janick Cardinale⁸, Craig Carthel⁹, Stefano Coraluppi⁹, Mark Winter¹⁰, Andrew R Cohen¹⁰, William J Godinez^{11,12}, Karl Rohr^{11,12}, Yannis Kalaidzidis^{13,14}, Liang Liang¹⁵, James Duncan¹⁵, Hongying Shen¹⁶, Yingke Xu¹⁷, Klas E G Magnusson¹⁸, Joakim Jaldén¹⁸, Helen M Blau¹⁹, Perrine Paul-Gilloteaux²⁰, Philippe Roudot²¹, Charles Kervrann²¹, François Waharte²⁰, Jean-Yves Tinevez²², Spencer L Shorte²², Joost Willemse²³, Katherine Celler²³, Gilles P van Wezel²³, Han-Wei Dan²⁴, Yuh-Show Tsai²⁴, Carlos Ortiz de Solórzano⁶, Jean-Christophe Olivo-Marin^{1,26} & Erik Meijering^{4,5,26}

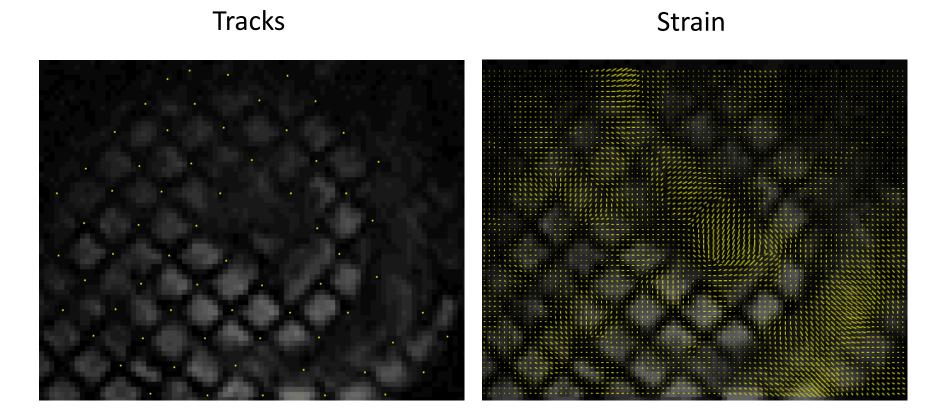
Particle tracking is of key importance for quantitative analysis of intracellular dynamic processes from time-lapse microscopy image data. Because manually detecting and following large numbers of individual particles is not feasible, automated computational methods have been developed for these tasks by many groups. Aiming to perform an objective comparison of methods, we gathered the community and organized an open competition in which participating teams applied their own methods independently to a commonly defined data sets.

processes is particle tracking. Here, a 'particle' may be anything from a single molecule to a macromolecular complex, organelle, virus or microsphere¹², and the task of detecting and following individual particles in a time series of images is often (somewhat confusingly) referred to as 'single-particle tracking'. As the number of particles may be very large (hundreds to thousands), requiring 'multiple-particle tracking'^{13–15}, manual annotation of the image data is not feasible, and computer algorithms are

Tracking Heart Motion in MRI

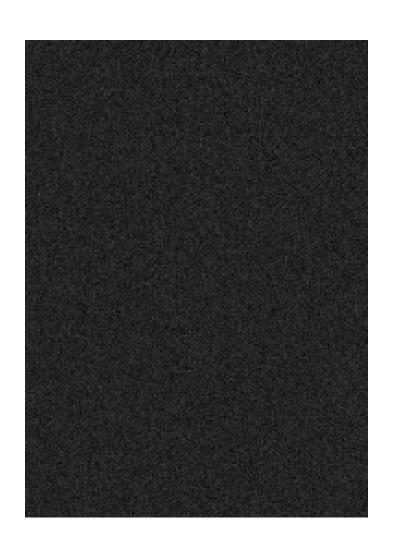


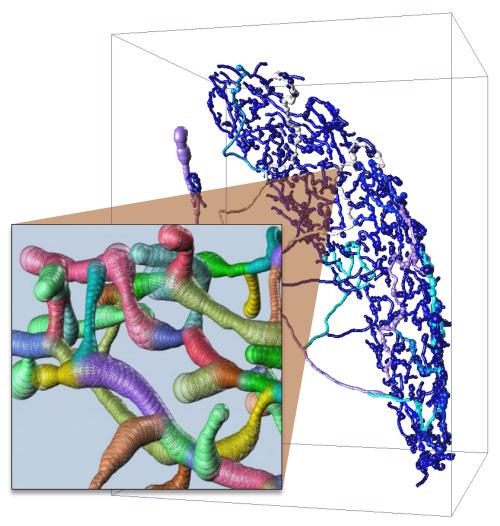
Tracking Heart Motion in MRI



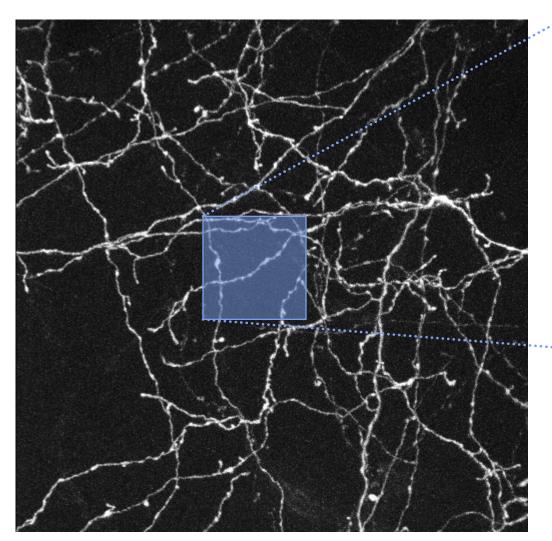
Smal & Meijering, Medical Image Analysis, 2012

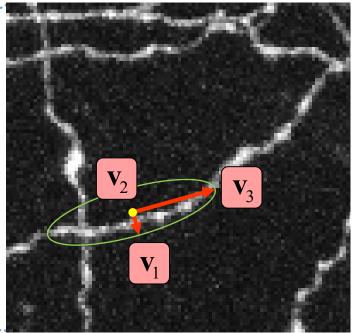
Neuron Reconstruction





Neuron Reconstruction

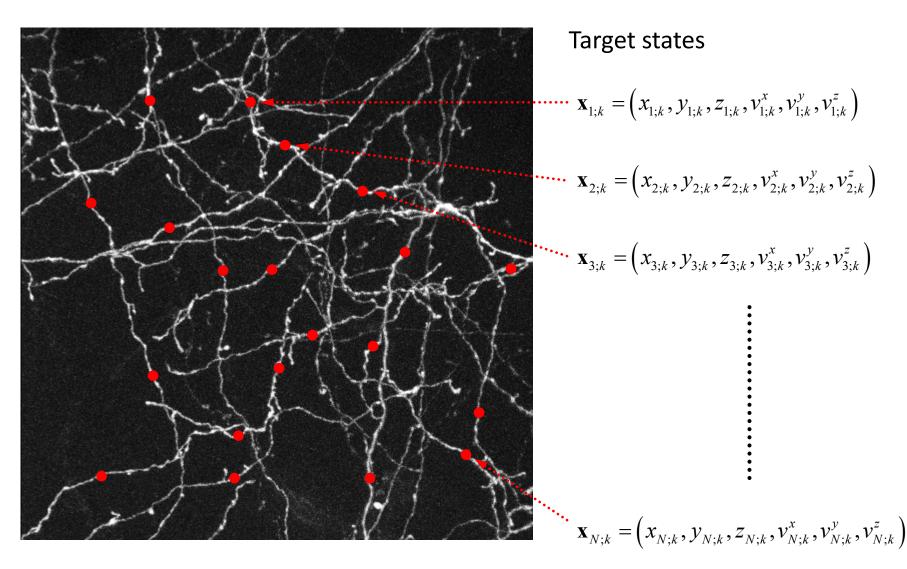




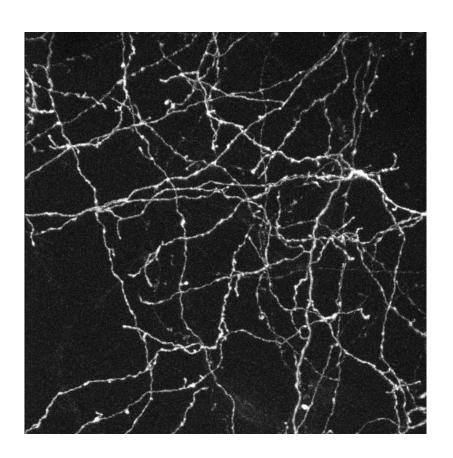
$$\mathbf{H} = \begin{pmatrix} I_{xx} & I_{xy} & I_{xz} \\ I_{yx} & I_{yy} & I_{yz} \\ I_{zx} & I_{zy} & I_{zz} \end{pmatrix} = \mathbf{V}^{\mathrm{T}} \cdot \mathbf{\Lambda} \cdot \mathbf{V}$$

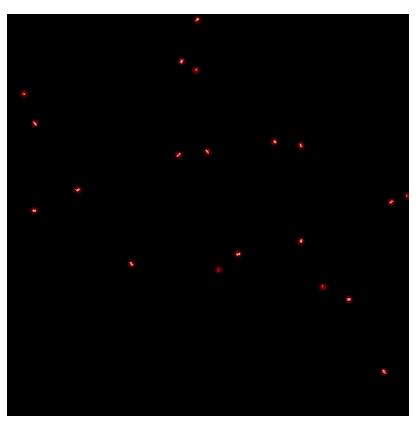
Seed points: $\lambda_3 \ll \lambda_2 \approx \lambda_1$

Neuron Reconstruction



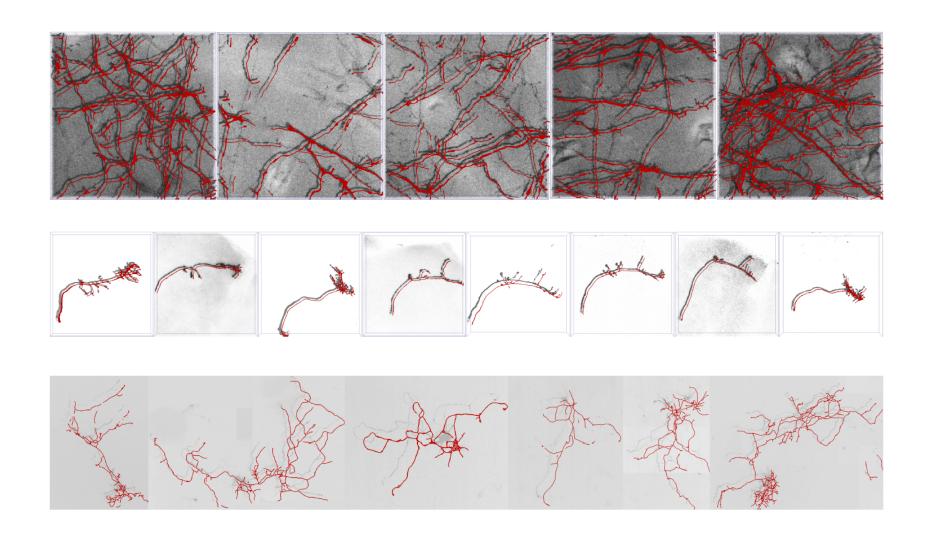
Tracking for Neuron Reconstruction





Radojevic & Meijering, Neuroinformatics, 2019

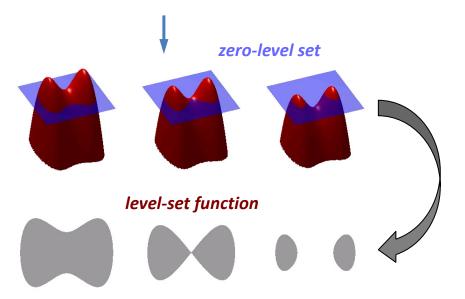
Neuron Reconstruction Results

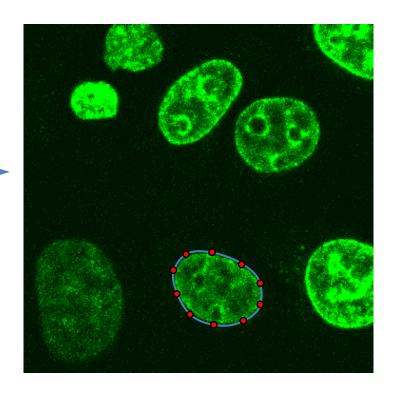


Cell Tracking

Popular segmentation methods

- Intensity thresholding
- Watershed segmentation
- Active contour fitting
- Level-set segmentation



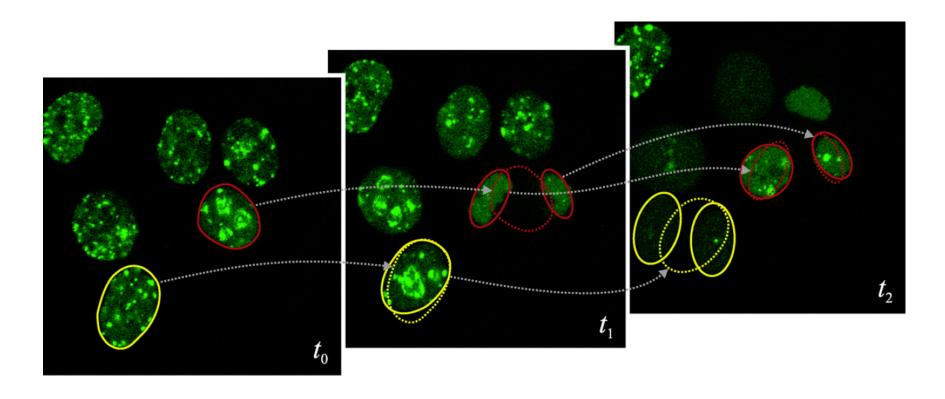


Model: $C(r) = \sum_{n} \mathbf{P}_{n} B(r - n)$

Fitting: $\hat{C} = \arg\min E(C)$

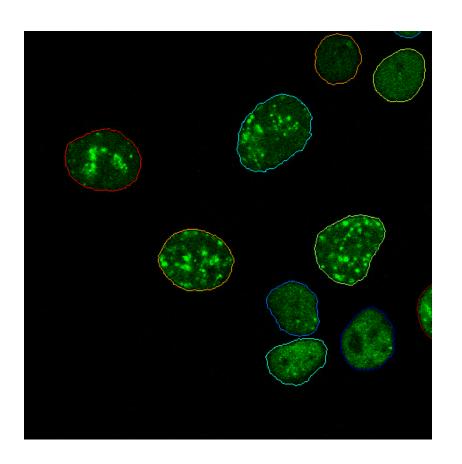
Cell Tracking

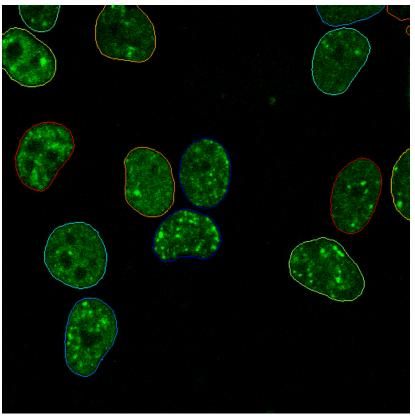
Linking by contour model evolution



Dzyubachyk & Meijering, IEEE Transactions on Medical Imaging, 2010

Cell Tracking





Coloured contours indicate the results of cell segmentation and indentification

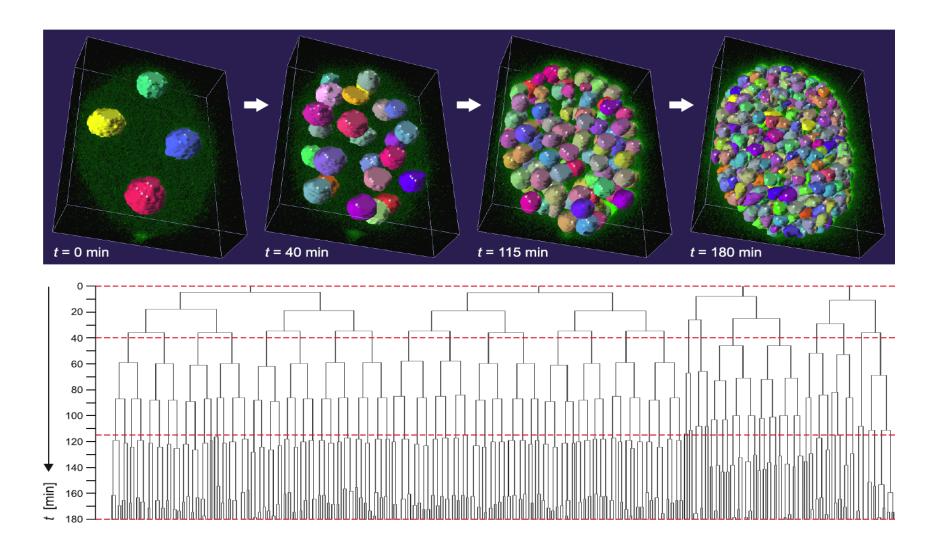
An objective comparison of cell-tracking algorithms

Vladimír Ulman^{1,24,25}, Martin Maška^{1,25}, Klas E G Magnusson², Olaf Ronneberger^{3,24}, Carsten Haubold⁴, Nathalie Harder^{5,24}, Pavel Matula¹, Petr Matula¹, David Svoboda¹, Miroslav Radojevic⁶, Ihor Smal⁶, Karl Rohr⁵, Joakim Jaldén², Helen M Blau⁷, Oleh Dzyubachyk⁸, Boudewijn Lelieveldt^{8,9}, Pengdong Xiao^{10,24}, Yuexiang Li^{11,24}, Siu-Yeung Cho¹², Alexandre C Dufour¹³, Jean-Christophe Olivo-Marin¹³, Constantino C Reyes-Aldasoro¹⁴, Jose A Solis-Lemus¹⁴, Robert Bensch³, Thomas Brox³, Johannes Stegmaier¹⁵, Ralf Mikut¹⁵, Steffen Wolf⁴, Fred A Hamprecht⁴, Tiago Esteves^{16,17}, Pedro Quelhas¹⁶, Ömer Demirel¹⁸, Lars Malmström¹⁸, Florian Jug¹⁹, Pavel Tomancak¹⁹, Erik Meijering⁶, Arrate Muñoz-Barrutia^{20,21}, Michal Kozubek¹ & Carlos Ortiz-de-Solorzano^{22,23}

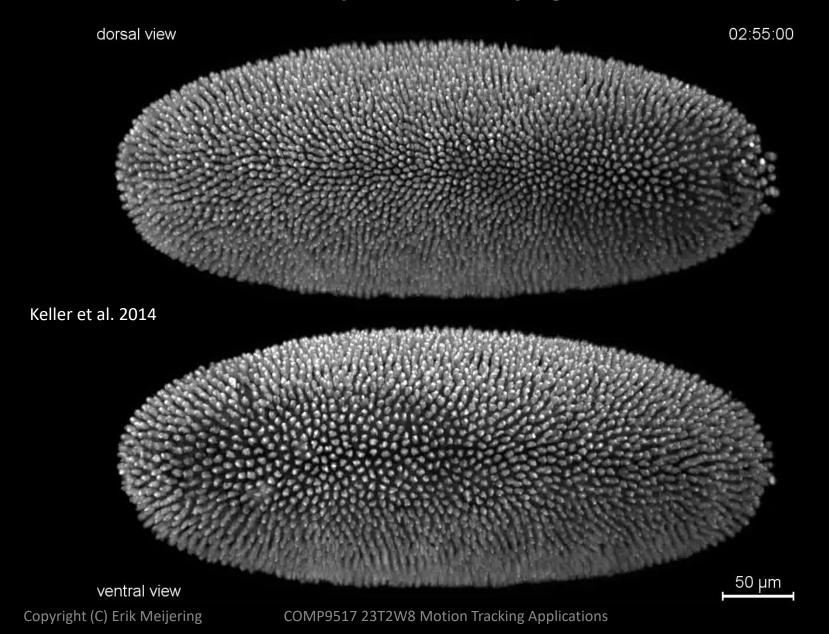
We present a combined report on the results of three editions of the Cell Tracking Challenge, an ongoing initiative aimed at promoting the development and objective evaluation of cell segmentation and tracking algorithms. With 21 participating algorithms and a data repository consisting of 13 data sets from various microscopy modalities, the challenge displays today's state-of-the-art methodology in the field. We analyzedythmickallendelsessuits using performance the assured to

these processes. Imaging techniques, such as phase contrast (PhC) or differential interference contrast (DIC) microscopy, make cells visible without the need of exogenous markers. Fluorescence microscopy, on the other hand, relies on fluorescent reporters to specifically label cell components such as nuclei, cytoplasm or membranes. These labeled structures are then imaged in two or three dimensions by various imaging modalities, including widefield, confocal,

Cell Lineage Reconstruction

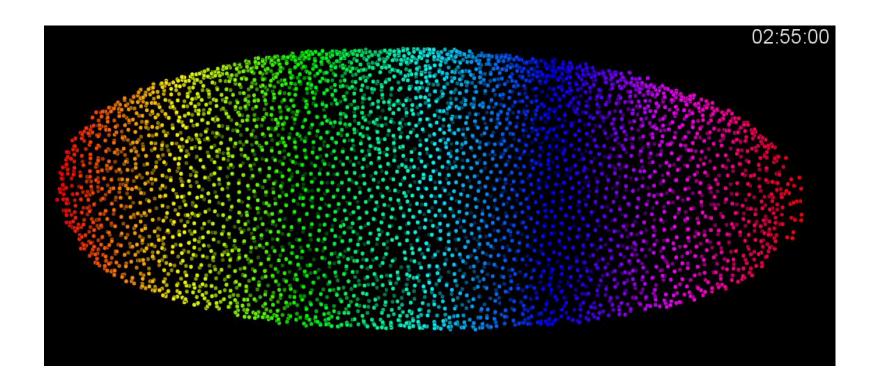


Drosophila embryogenesis



Cell Lineage Reconstruction

Tracking each cell during Drosophila embryonic development



Keller et al., Nature Methods, 2014

References and Acknowledgements

Further information on the presented applications can be found in the following papers:

- Image Registration for Digital Subtraction Angiography
- Advanced Level-Set Based Cell Tracking in Time-Lapse Fluorescence Microscopy
- Multimodal Volume Registration by Maximization of Mutual Information
- Optical-Flow Based Non-Invasive Analysis of Cardiomyocyte Contractility
- Multiple Object Tracking in Molecular Bioimaging by RBM Particle Filtering
- Objective Comparison of Particle Tracking Methods
- Reversible Jump MCMC Methods for Fully Automatic Motion Analysis in Tagged MRI
- Automated Neuron Tracing Using Probability Hypothesis Density Filtering
- An Objective Comparison of Cell-Tracking Algorithms
- Methods for Cell and Particle Tracking
- Reconstruction of Cell Lineages From Large-Scale Fluorescence Microscopy Data
- A Tutorial on Particle Filters for Online Nonlinear/Non-Gaussian Bayesian Tracking