COMP9517

Computer Vision

2023 Term 2 Week 1

Professor Erik Meijering

Introduction

UNSW SYDNEY

What is computer vision?

Computer science perspective

Computer vision is the interdisciplinary field that develops theories and methods to allow computers extract relevant information from digital images or videos

Computer engineering perspective

Computer vision is the interdisciplinary field that develops algorithms and tools to automate perceptual tasks normally performed by the human visual system

Every picture tells a story

"A picture is worth a thousand words"

Computer vision

automates and integrates many information processing and representation approaches useful for visual perception

https://en.wikipedia.org/wiki/montparnasse_derailment

Can computers match (or beat) humans?

Yes and **No**

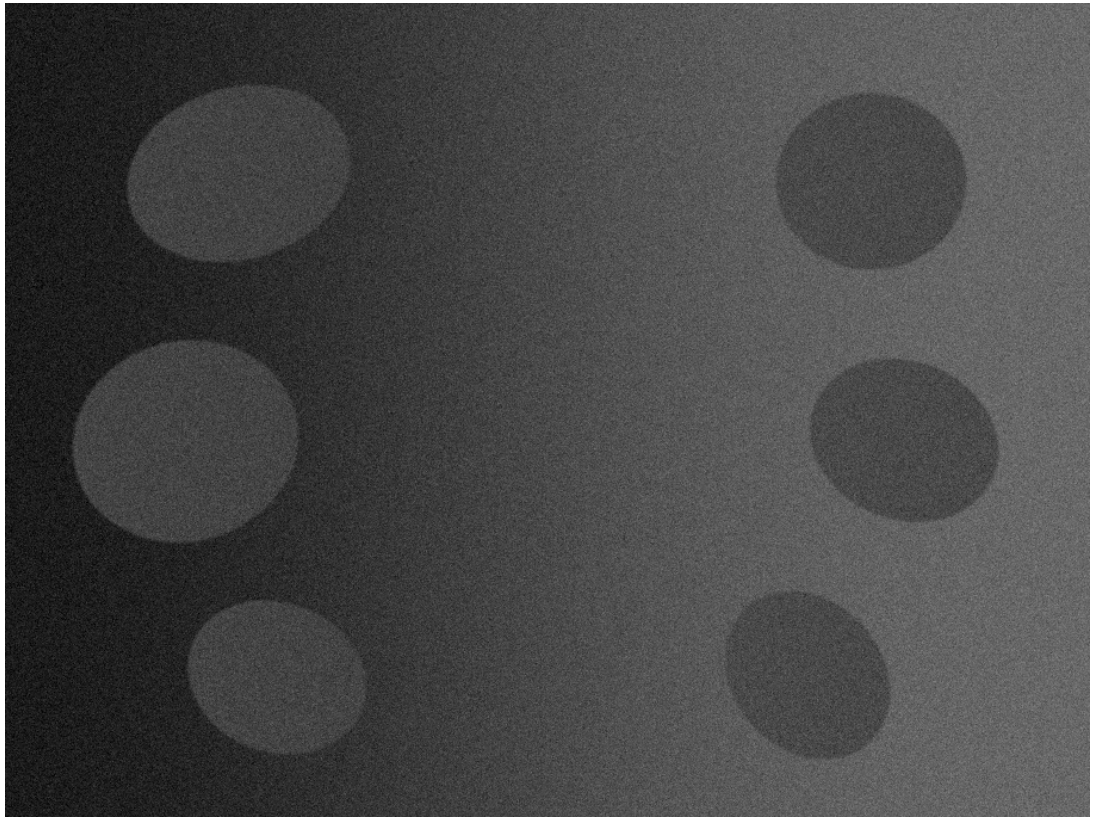
- Humans are still better at “hard” tasks

  Ambiguous data, leveraging prior knowledge, continual learning, working across applications

- Computers can be better at “easy” tasks

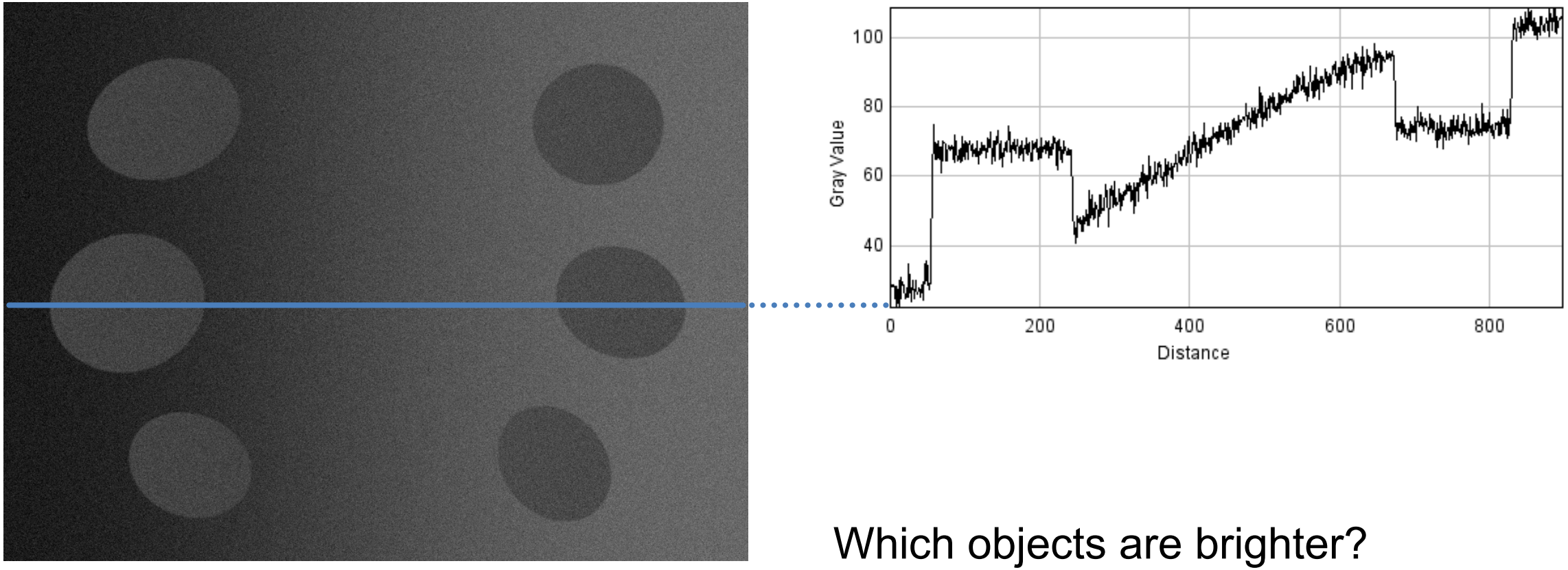
  High-quality data, using mathematical models, consistent training set, single well-defined application

Human vision has its limitations…



Which objects are brighter?

Human vision has its limitations…



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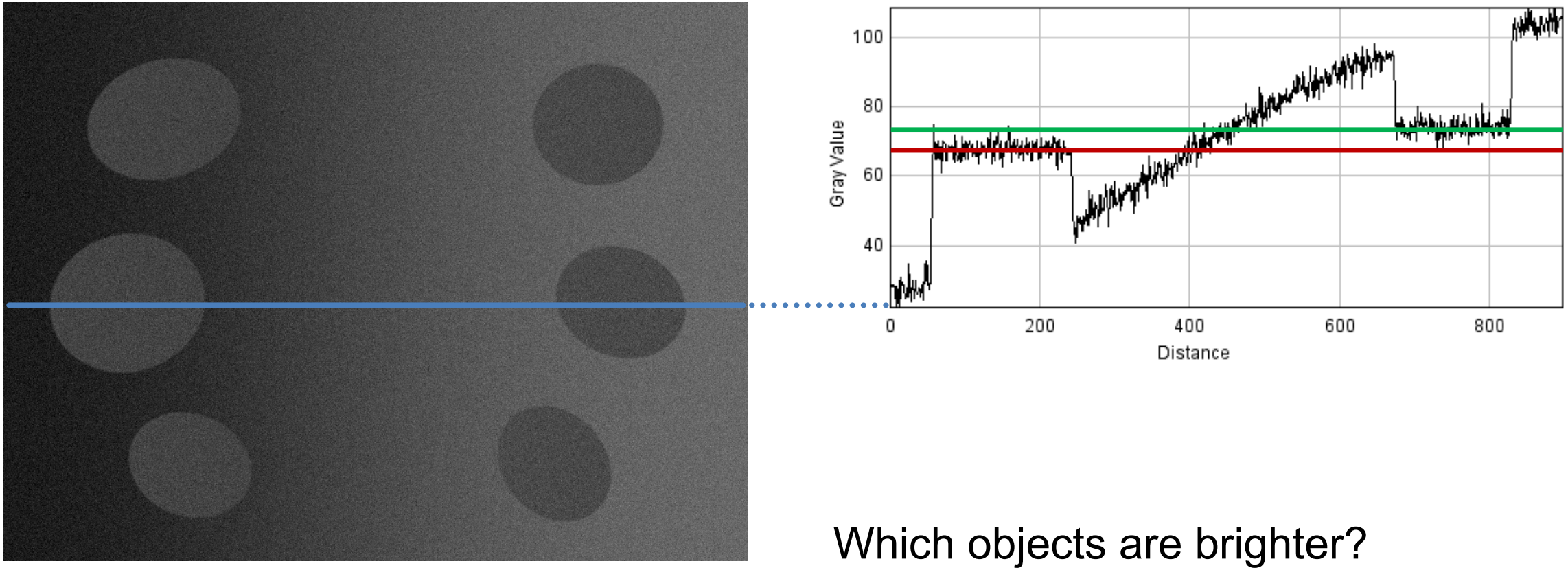

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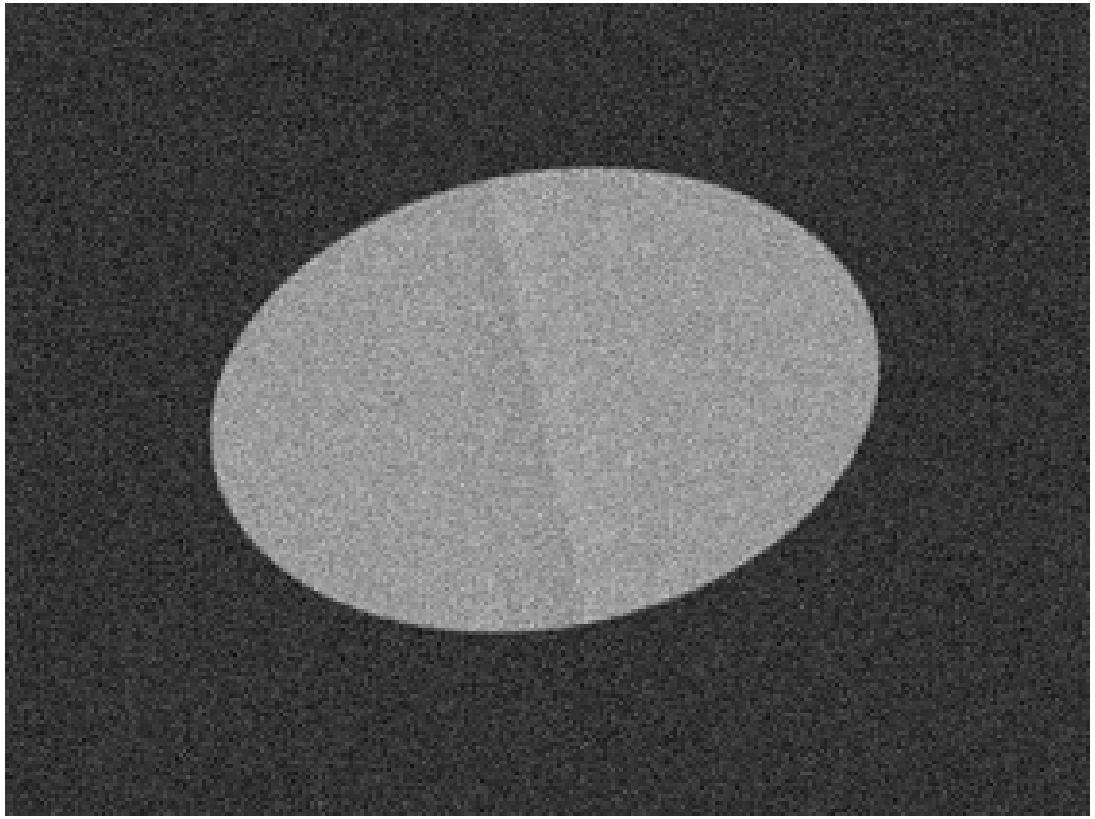

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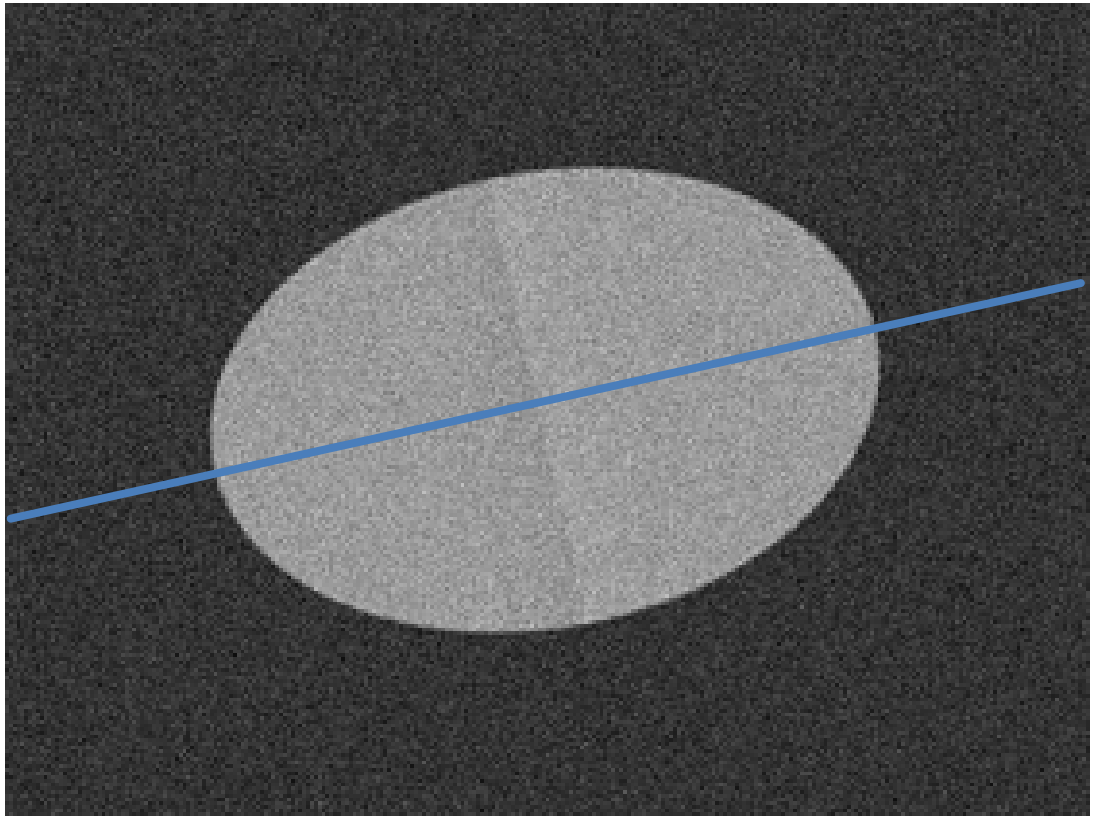

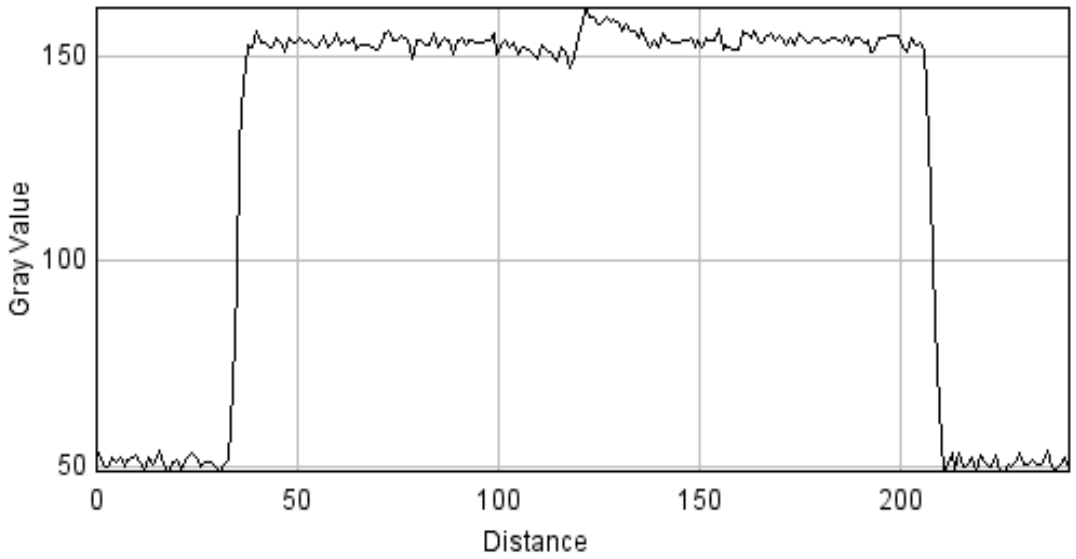

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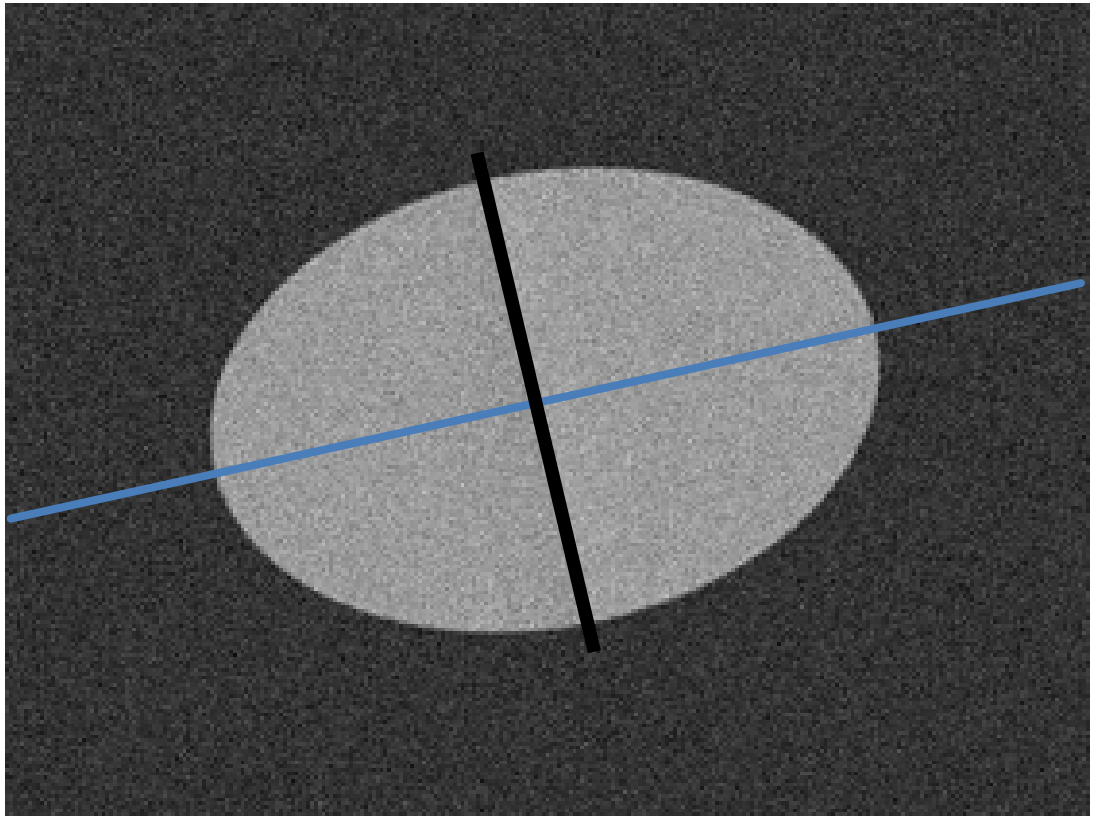

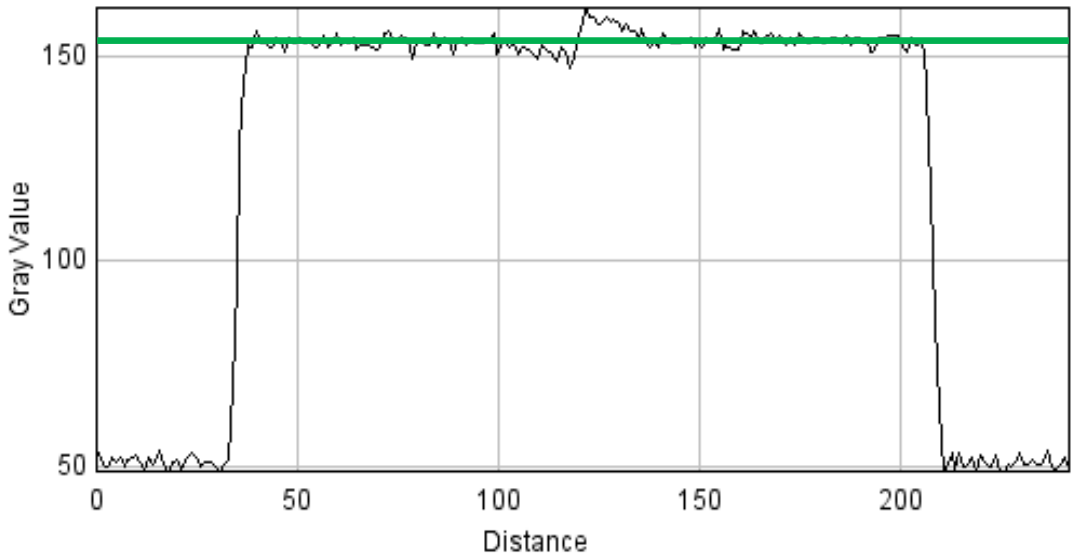

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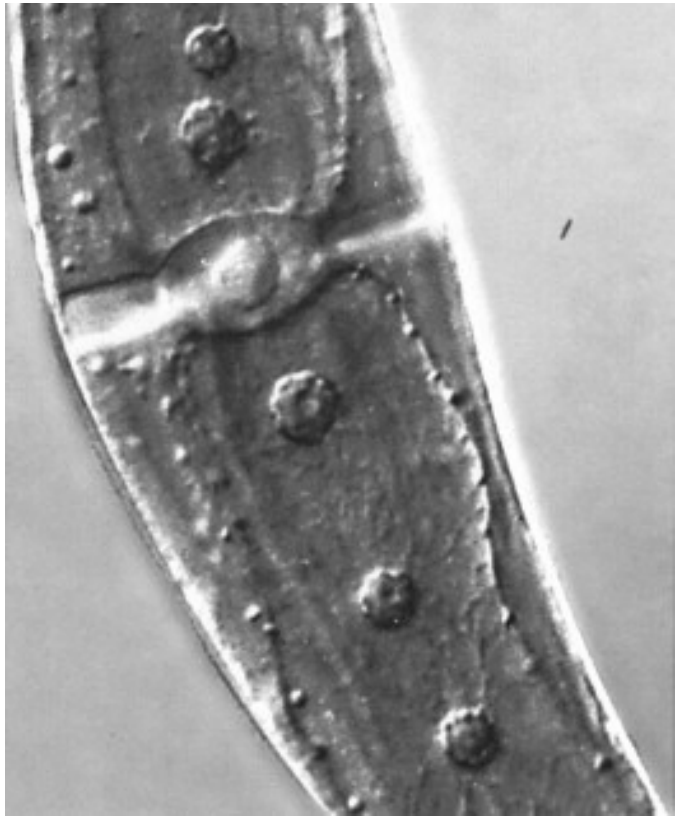
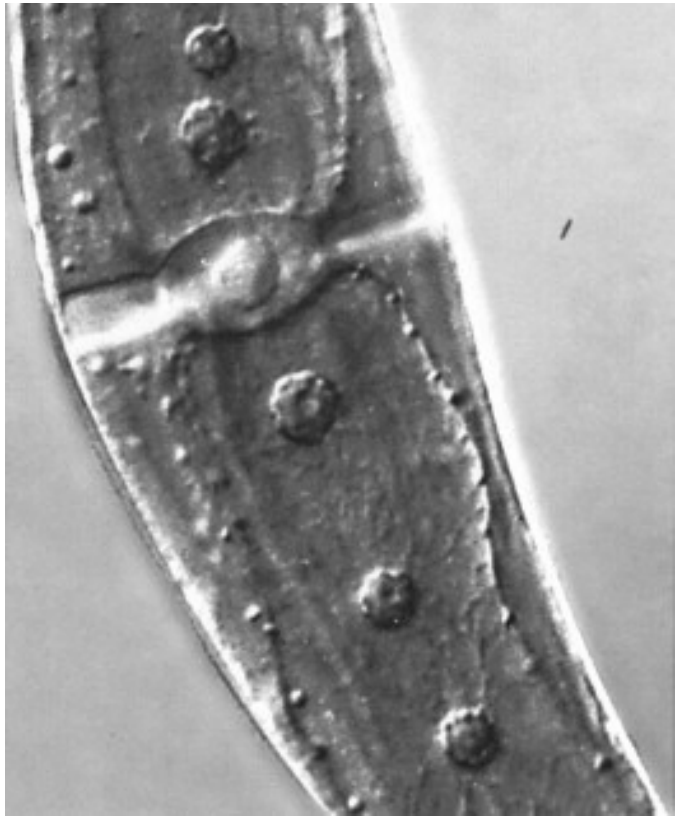
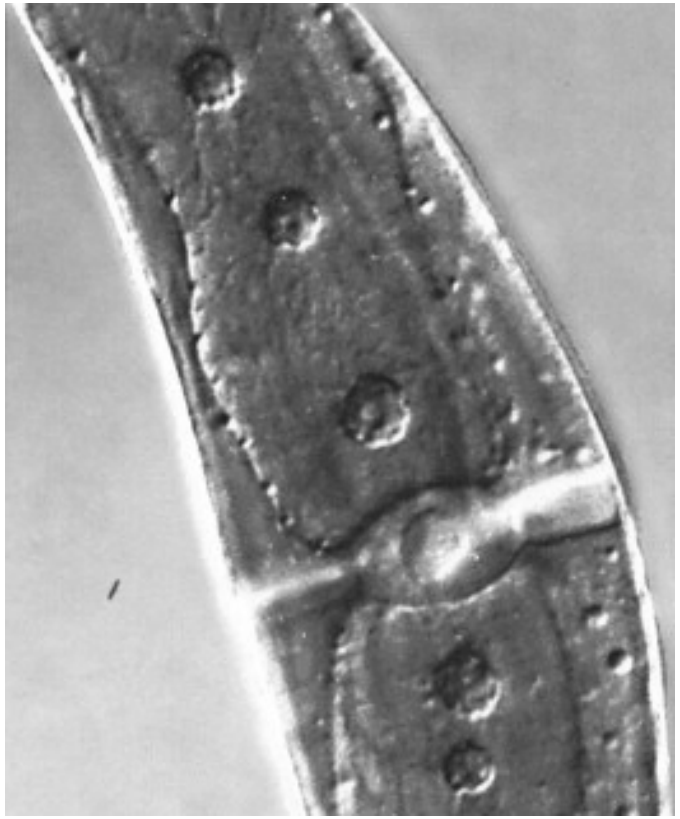


Are the cells popping in or out?

Human vision has its limitations…



180°



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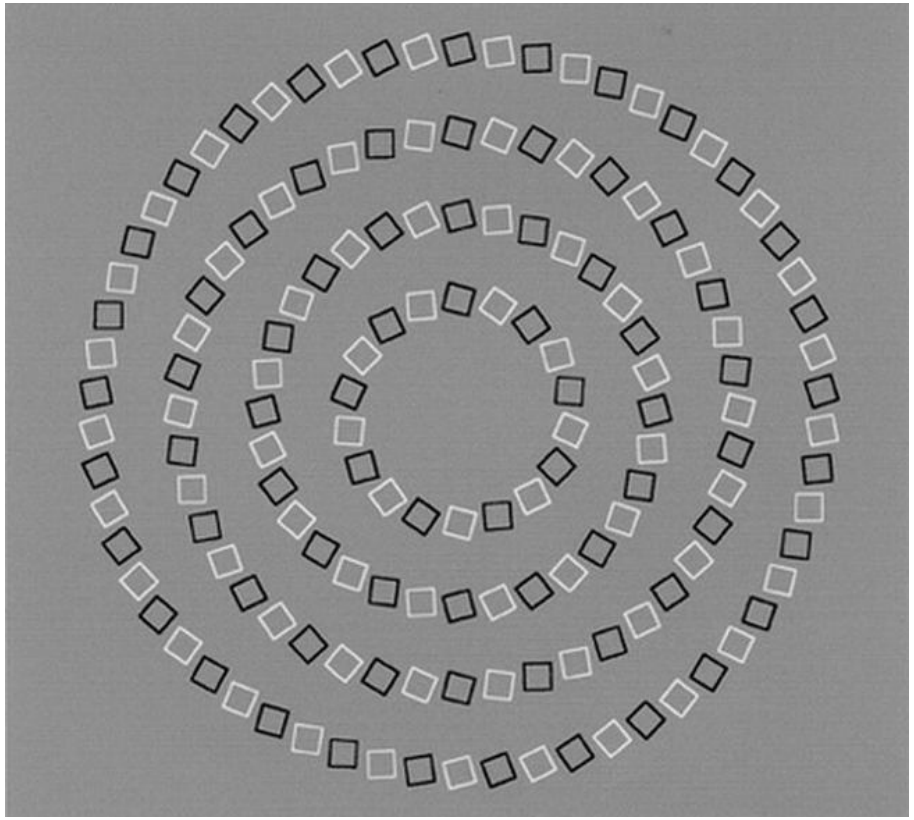
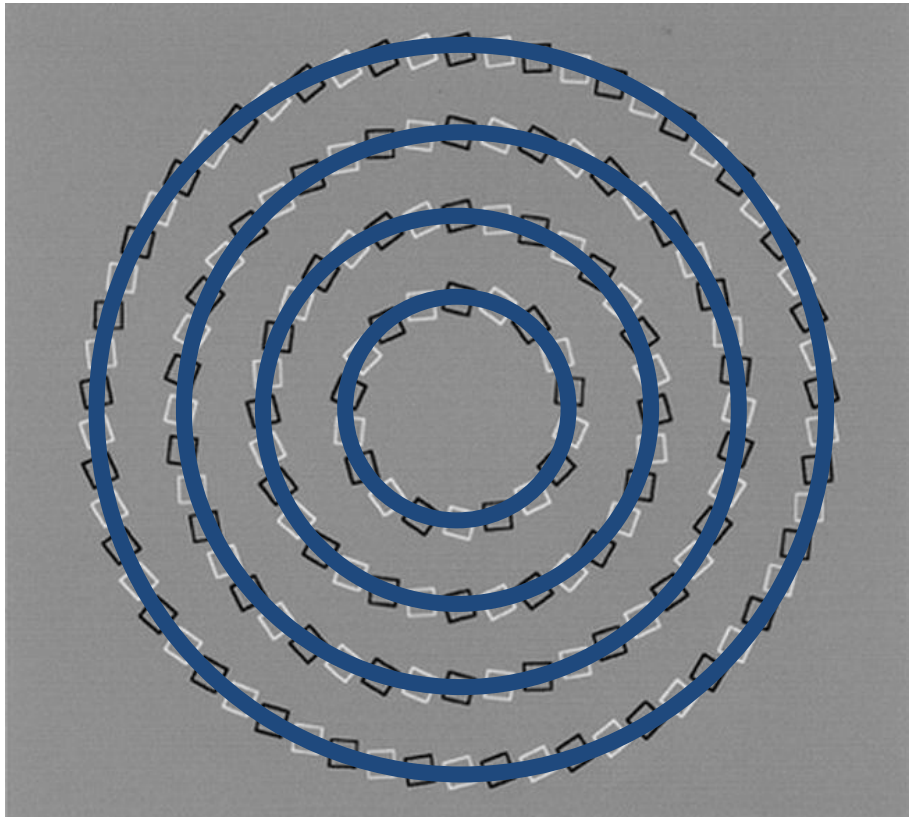


What pattern do the squares form?

Human vision has its limitations…



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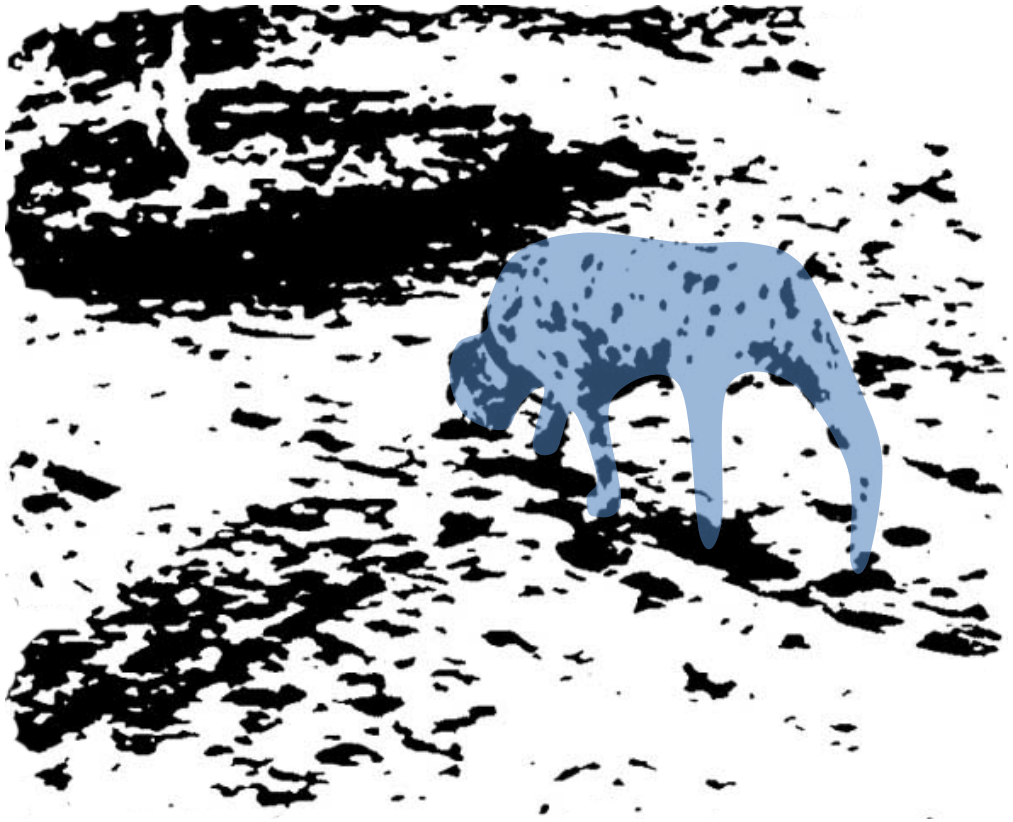
Human vision has its limitations…

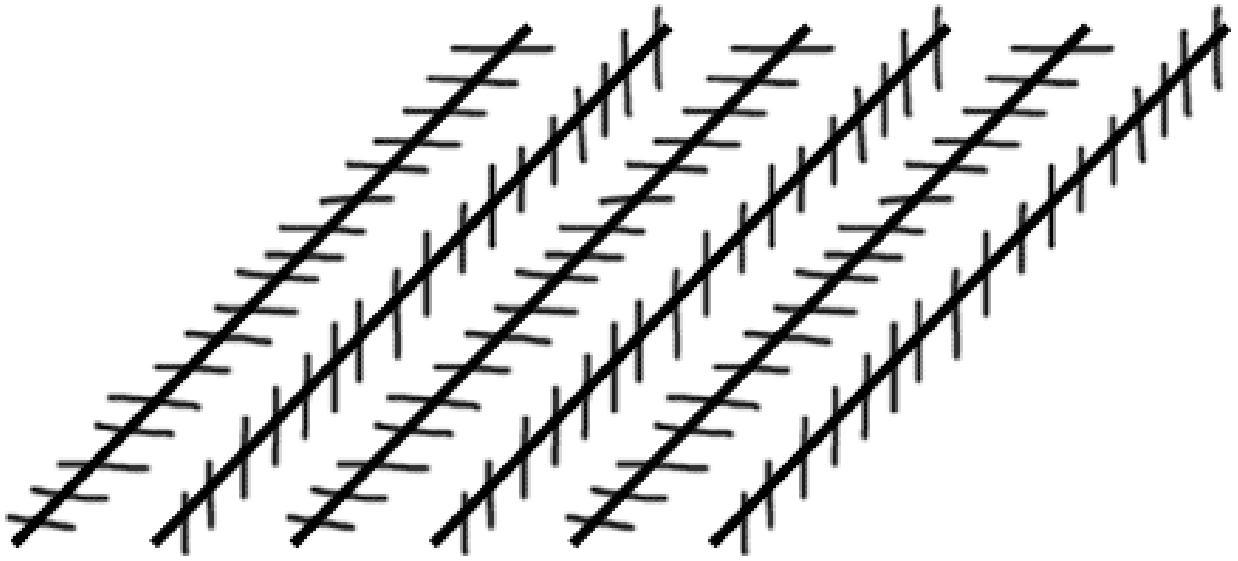
What object do you see in this image?

Human vision has its limitations…



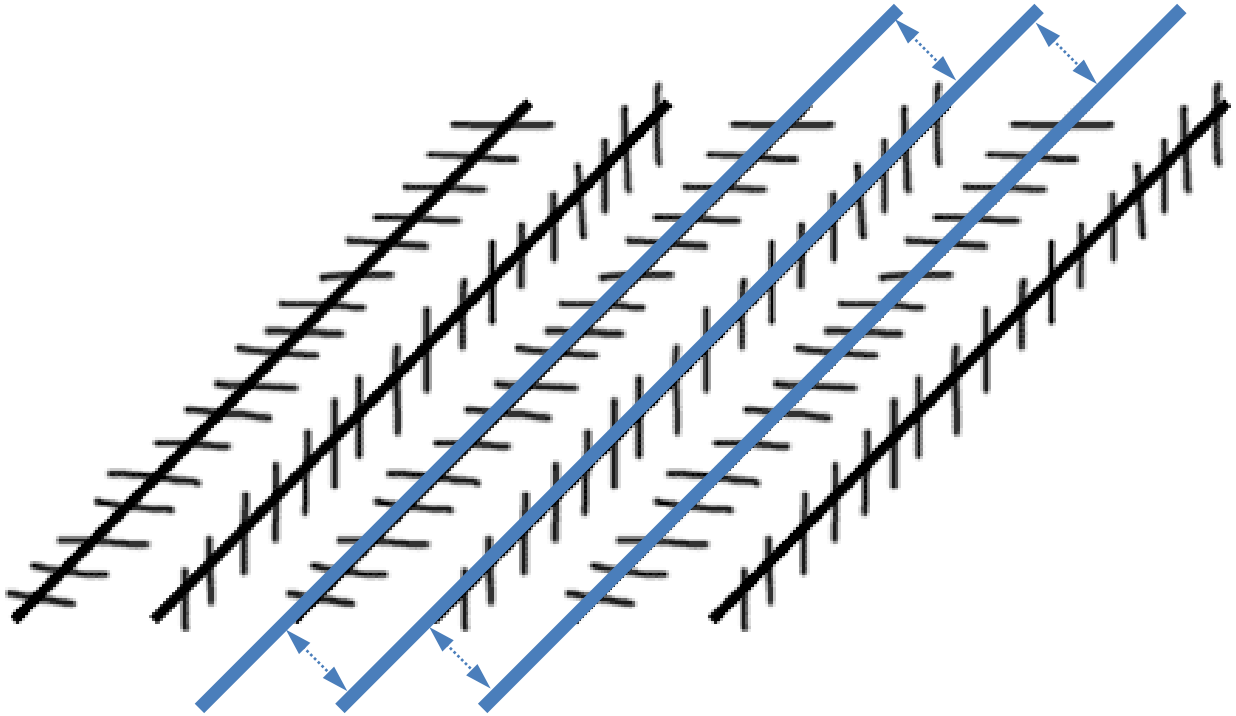
What object do you see in this image?

Human vision has its limitations…



How do the main lines run with respect to each other?

Human vision has its limitations…



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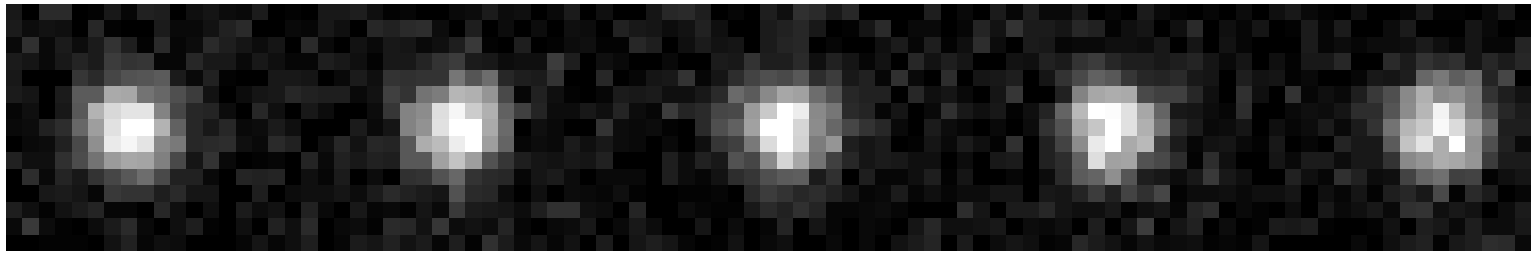


In which direction are these particles moving ?

Human vision has its limitations…

https://www.youtube.com/watch?v=a7efEqgpIrE

Course rationale

Human vision has its limitations

- Intensities, shapes, patterns, motions can be misinterpreted
- Is labor intensive, time-consuming, subjective, error-prone

Computer vision can potentially improve this

- Computers can work day and night without getting tired
- Analyze information quantitatively and objectively
- Potentially more accurate, precise, reproducible

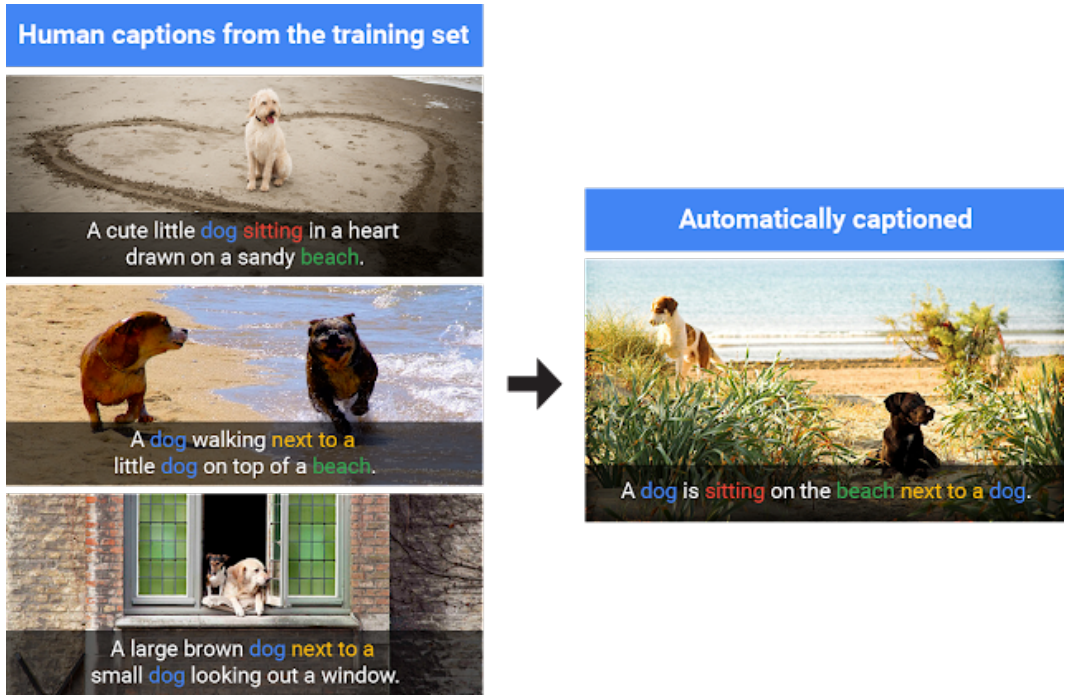
If the methods and tools are well designed!

Application: 3D shape reconstruction

Project VarCity recreates 3D city models using social media photos

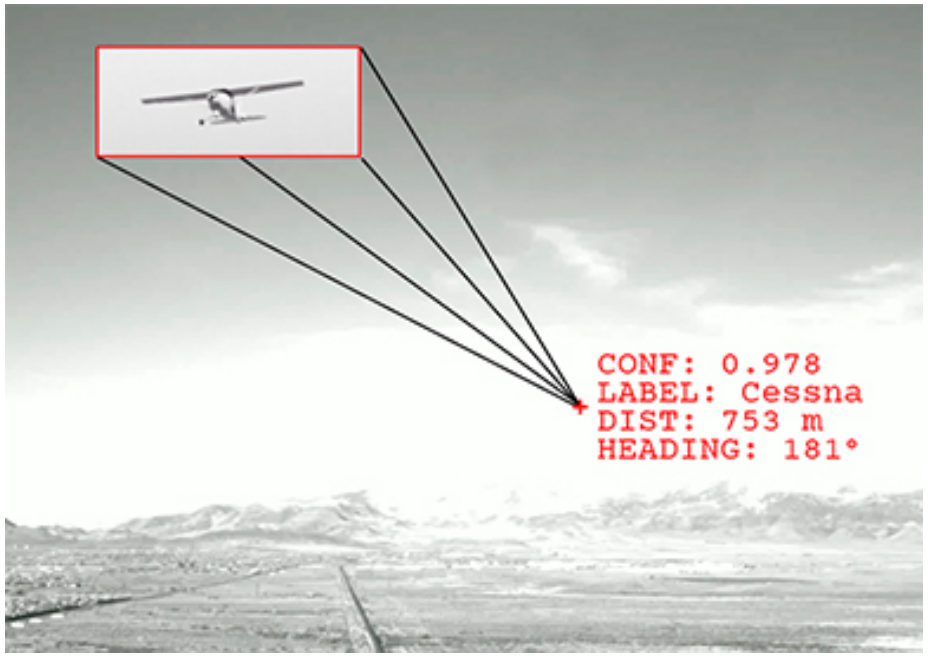
Application: image captioning

Google's Show and Tell open-source image captioning model in TensorFlow



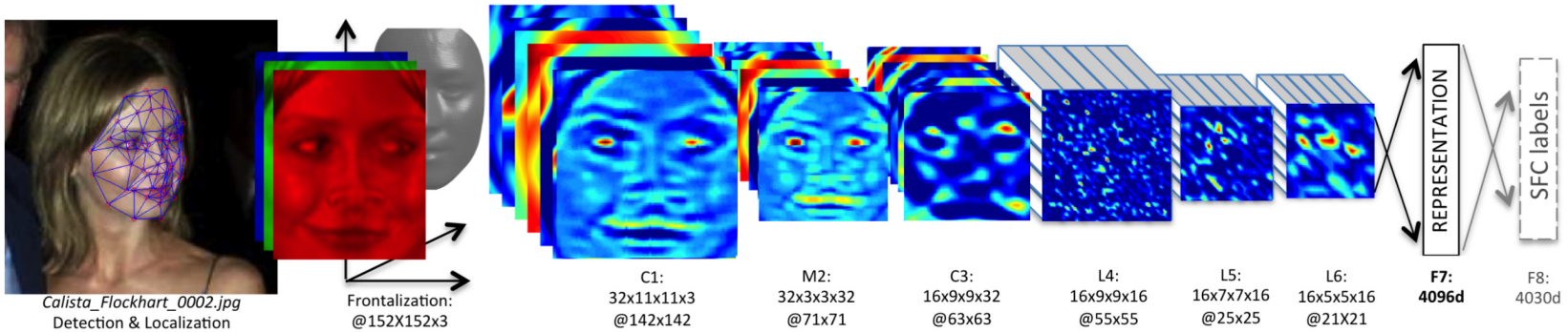
Application: intelligent collision avoidance

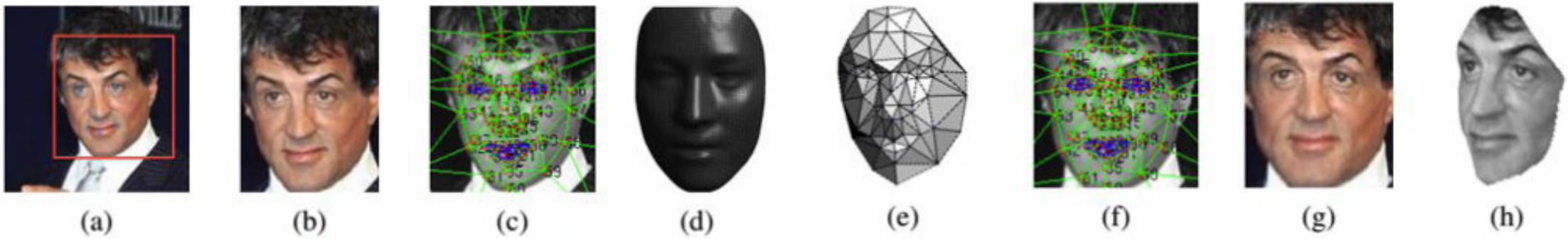
Iris Automation provides safer drone operation with intelligent collision avoidance



Application: face detection and recognition

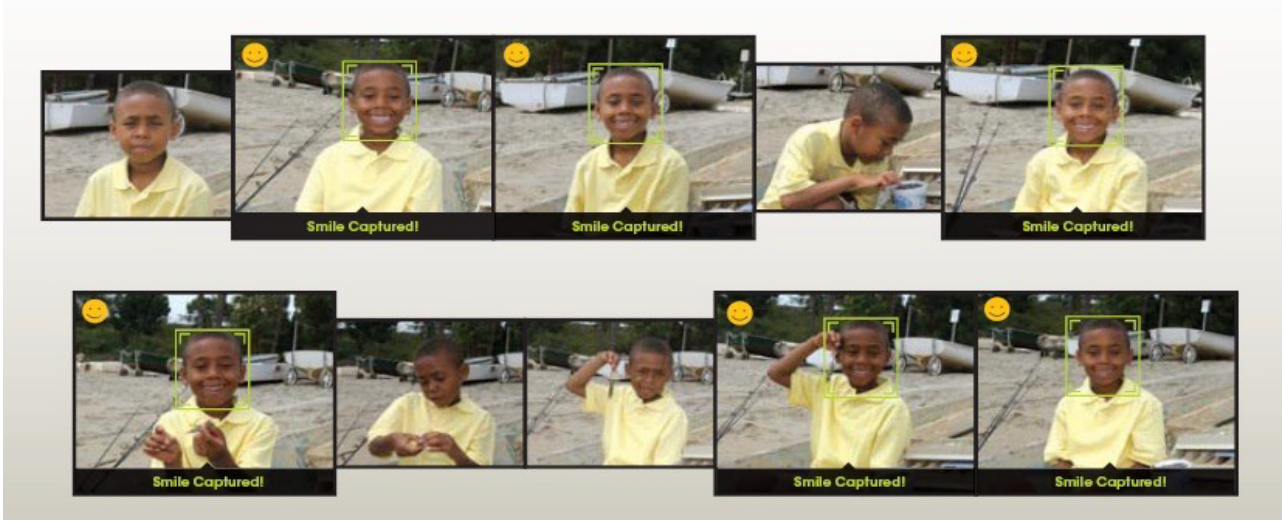
Facebook's DeepFace project nears human accuracy in identifying faces



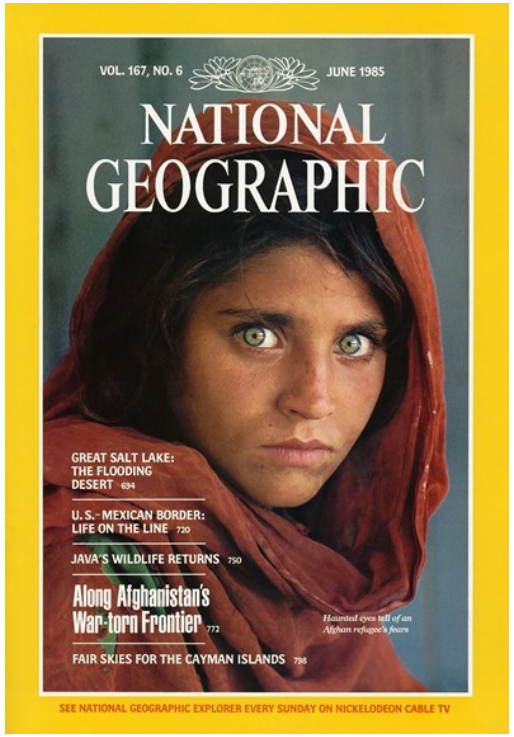


Application: face detection and recognition

For improving image capture on digital cameras



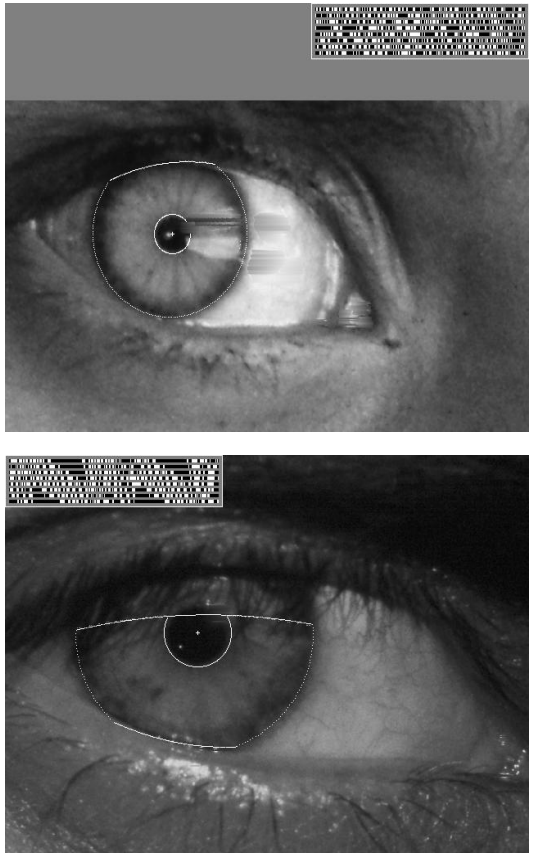
Application: vision-based biometrics



Who is she?

[How the Afghan girl was identified by her iris patterns]

The remarkable story of Sharbat Gula, first photographed in 1984 aged 12 in a refugee camp in Pakistan by National Geographic photographer Steve McCurry, and traced 18 years later to a remote part of Afghanistan where she was again photographed by McCurry…



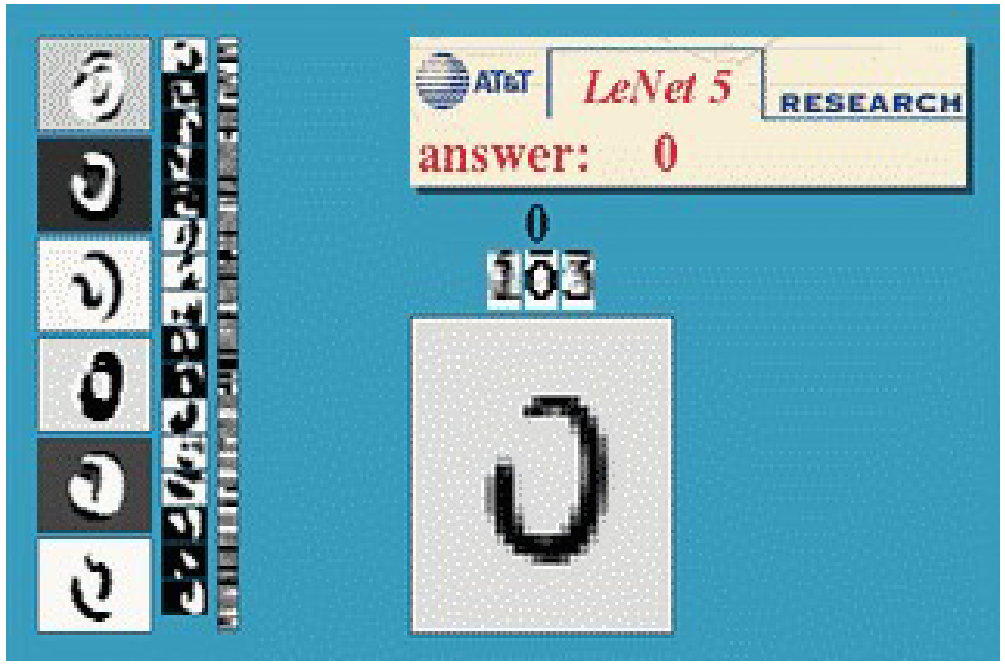
Application: logging in without a password

Fingerprint scanners on modern laptops and other devices

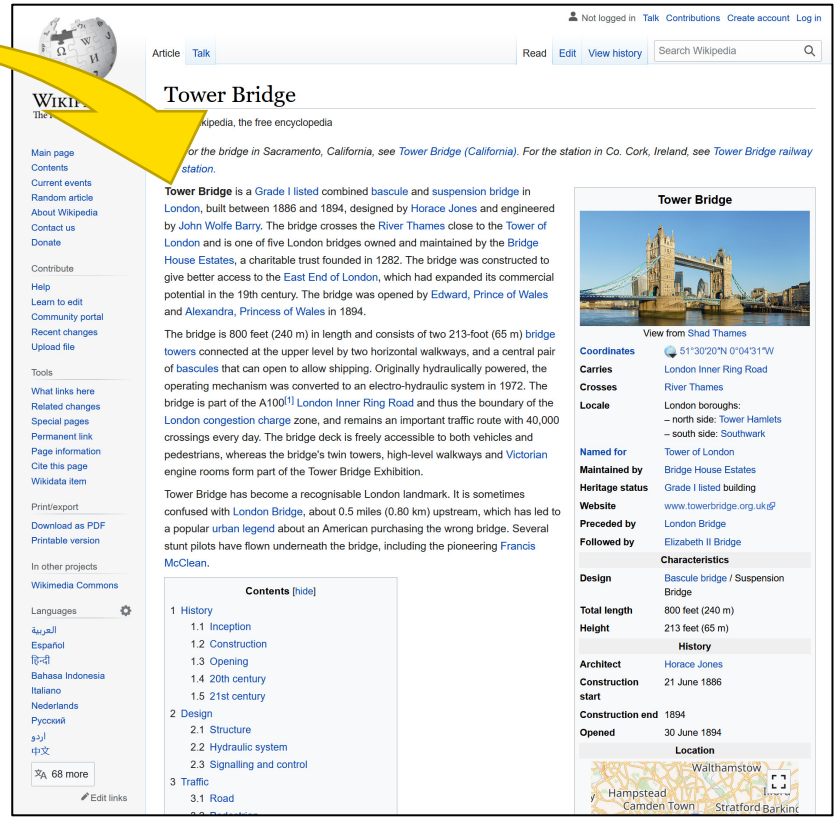
Windows Hello makes logging in as easy as looking at your PC

Application: optical character recognition (OCR)

Converting scanned documents or number plates to processable text



Application: landmark recognition



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Tower Bridge

...kipedia, the free encyclopedia

...or the bridge in Sacramento, California, see Tower Bridge (California). For the station in Co. Cork, Ireland, see Tower Bridge railway ... station.

Tower Bridge is a Grade I listed combined bascule and suspension bridge in London, built between 1886 and 1894, designed by Horace Jones and engineered by John Wolfe Barry. The bridge crosses the River Thames close to the Tower of London and is one of five London bridges owned and maintained by the Bridge House Estates, a charitable trust founded in 1282. The bridge was constructed to give better access to the East End of London, which had expanded its commercial potential in the 19th century. The bridge was opened by Edward, Prince of Wales and Alexandra, Princess of Wales in 1894.

The bridge is 800 feet (240 m) in length and consists of two 213-foot (65 m) bridge towers connected at the upper level by two horizontal walkways, and a central pair of bascules that can open to allow shipping. Originally hydraulically powered, the operating mechanism was converted to an electro-hydraulic system in 1972. The bridge is part of the A100[1] London Inner Ring Road and thus the boundary of the London congestion charge zone, and remains an important traffic route with 40,000 crossings every day. The bridge deck is freely accessible to both vehicles and pedestrians, whereas the bridge's twin towers, high-level walkways and Victorian engine rooms form part of the Tower Bridge Exhibition.

Tower Bridge has become a recognisable London landmark. It is sometimes confused with London Bridge, about 0.5 miles (0.80 km) upstream, which has led to a popular urban legend about an American purchasing the wrong bridge. Several stunt pilots have flown underneath the bridge, including the pioneering Francis McClean.

Contents [hide]

1 History
- 1.1 Inception
- 1.2 Construction
- 1.3 Opening
- 1.4 20th century
- 1.5 21st century

2 Design
- 2.1 Structure
- 2.2 Hydraulic system
- 2.3 Signalling and control

3 Traffic
- 3.1 Road

Tower Bridge

View from Shad Thames

Coordinates	51°30'20"N 0°04'31"W
Carries	London Inner Ring Road
Crosses	River Thames
Locale	London boroughs: – north side: Tower Hamlets – south side: Southwark
Named for	Tower of London
Maintained by	Bridge House Estates
Heritage status	Grade I listed building
Website	www.towerbridge.org.uk
Preceded by	London Bridge
Followed by	Elizabeth II Bridge
Characteristics	
Design	Bascule bridge / Suspension Bridge
Total length	800 feet (240 m)
Height	213 feet (65 m)
History	
Architect	Horace Jones
Construction start	21 June 1886
Construction end	1894
Opened	30 June 1894
Location	

Walthamstow Hampstead Camden Town Stratford Barking

Application: autonomous vehicles

Intel's Mobileye makes cars safer and more autonomous

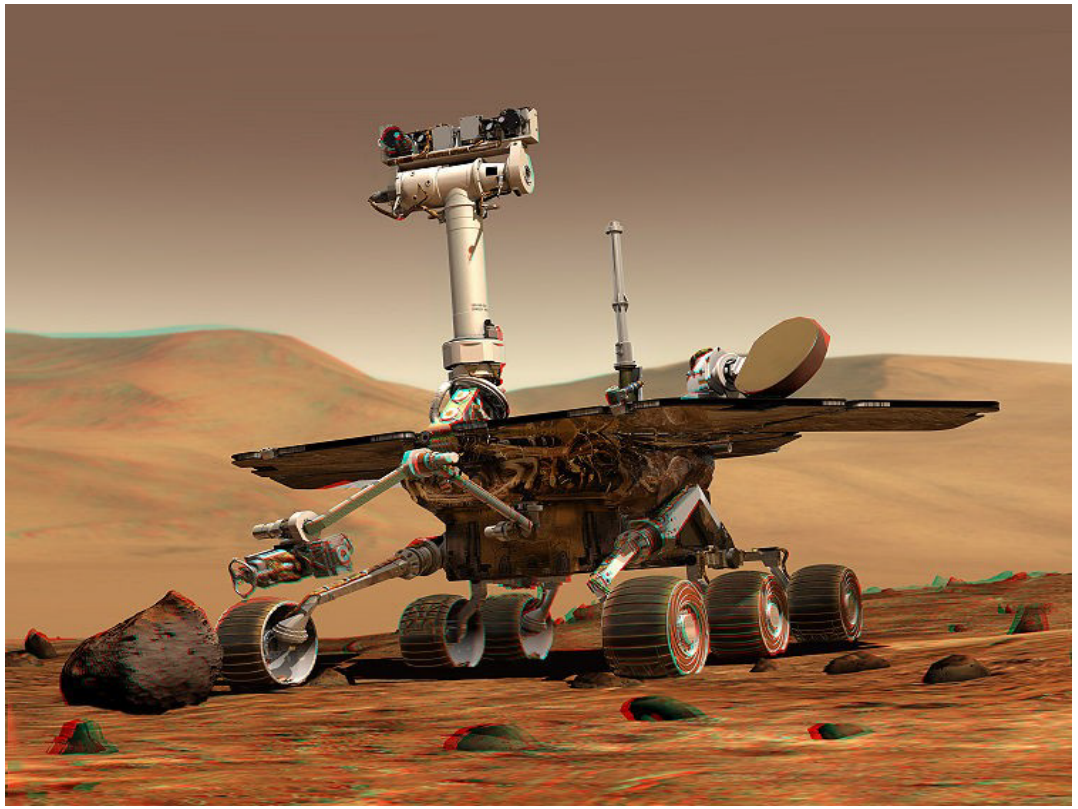
Application: space exploration

NASA's Mars Exploration Rover Spirit autonomously captured this picture in 2007

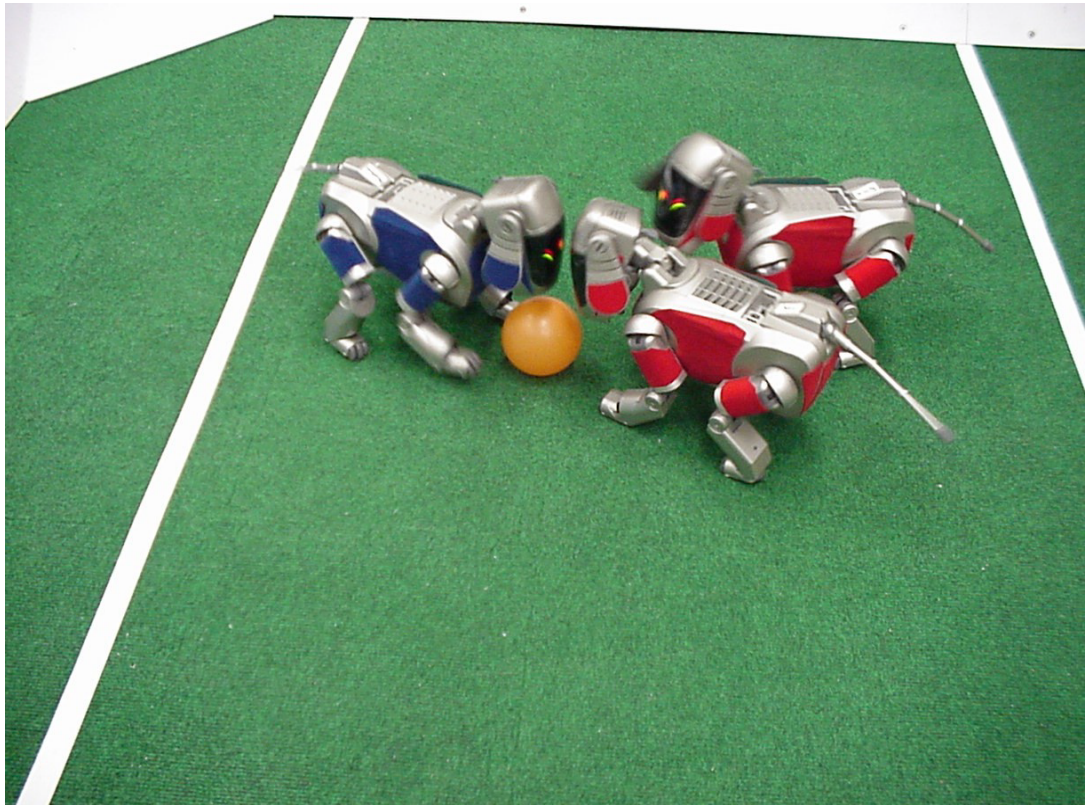
Vision systems used for panorama stitching, 3D terrain modeling, obstacle detection, position tracking

See Computer Vision on Mars for more information

Application: machine vision in robotics

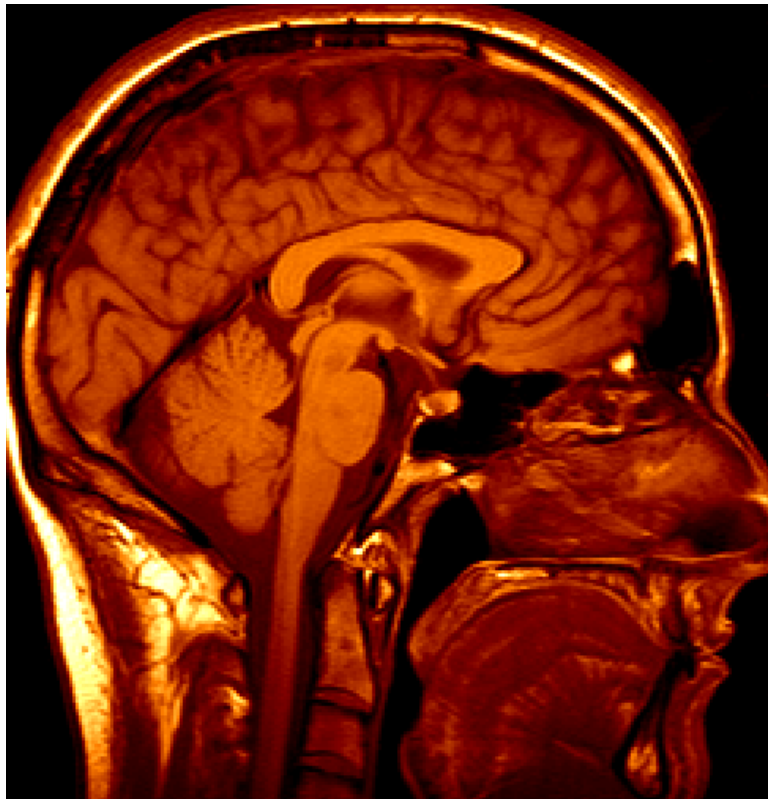


NASA's Mars Spirit Rover



RoboCup

Application: medical imaging

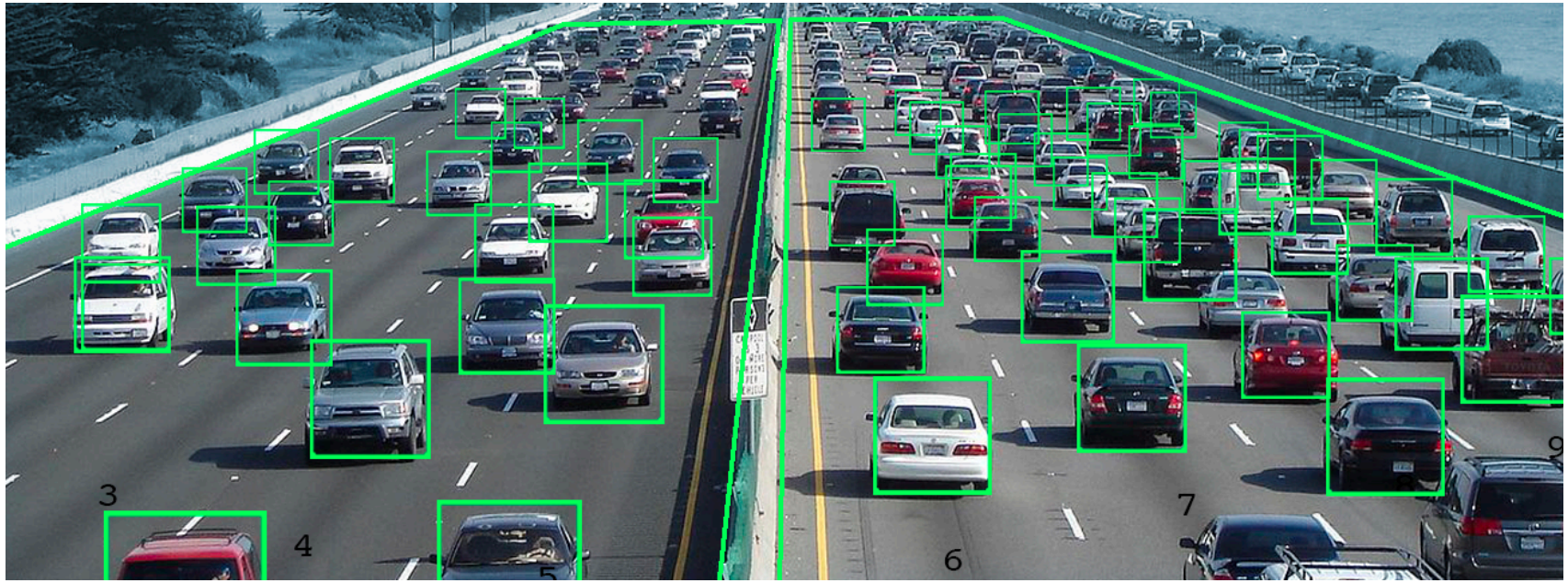


Computer Aided Diagnosis

Image Guided Surgery

Application: video surveillance

Software from TrafficVision turns traffic cameras into an intelligent sensors



- Traffic monitoring
- Action recognition
- Incident detection
- Speed estimation
- Vehicle counting
- ...

Goals and challenges of computer vision

- Extract useful information from images, both metric and semantic
- Data heterogeneity, ambiguity, and complexity are a big challenge
- Significant progress in recent years due to various improvements:
  - Processing power
  - Memory capacity
  - Storage capacity
  - Data availability
- Careful design of every step in the computer vision workflow:

  images > measurements > representation > algorithms for learning and inference

Computer vision tasks

- Obtain simple inferences from individual pixel values
- Group pixels to separate object regions or infer shape information
- Recognise objects using geometric or statistical pixel information
- Combine information from multiple images into a coherent whole

Requires understanding of the **physics of imaging** and the use of **mathematical and statistical models** for information extraction

Low-level computer vision

This concerns mostly **image processing** (image in > image out)

- **Sensing**: image capture and digitization
- **Preprocessing**: suppress noise and enhance object features
- **Segmentation**: separate objects from background and partition them
- **Description**: compute feature maps which differentiate objects
- **Labeling**: assign labels to image segments (regions of interest)

High-level computer vision

This concerns deeper **image analysis** (image in > knowledge out)

- **Detection**: detect, localize, count objects of interest
- **Recognition**: identify object types based on low-level information
- **Classification**: assign unique labels to recognized objects
- **Interpretation**: assign meaning to groups of recognized objects
- **Scene analysis**: complete understanding of the captured scene

Assumed knowledge

To do this course successfully you should:

- Be able to program well in **Python** or willing to learn it independently
- Be familiar with **data structures and algorithms** and basic **statistics**
- Be able/learn to **use software packages** (OpenCV, Scikit-Learn, Keras)
- Be familiar with **vector calculus and linear algebra** or willing to learn it

Please self-assess **before** deciding to stay/enroll in the course

Student learning outcomes

After completing this course, you will be able to:

- **Explain** basic scientific and engineering approaches to computer vision
- **Implement and test** computer vision algorithms using existing software
- **Build** larger computer vision applications by integrating software modules
- **Interpret and comment** on articles in the computer vision literature

Course topics and lecturers

Week	Topic	Lecturer
1	Introduction & Image Formation	Professor Erik Meijering
2	Image Processing	Professor Erik Meijering
3	Feature Representation	Dr Dong Gong
4	Image Segmentation	Professor Erik Meijering
5	Pattern Recognition	Dr Dong Gong
6	Flexible Week (No Lectures)	
7	Deep Learning	Dr Dong Gong
8	Motion and Tracking	Professor Erik Meijering
9	Applications	Dr Tariq Khan, Dr Sonit Singh, Dr Lian Xu
10	Project Demos	Student Project Group Presentations and Q&A

Weekly class structure

- **Lectures**: Mondays 12-2pm & Fridays 1-2/3pm (live stream via BB Collab)
  Monday lectures will be on campus and online with an opportunity to ask questions
- **Lab consultations**: Fridays 2-3pm in weeks 2,4,5 (online via BB Collab)
  Software demos and lab consultations with your assigned tutor in weeks 2,4,5
- **Project consultations**: Fridays 2-3pm in weeks 6-9 (online via BB Collab)
  All project consultations will be online with your assigned tutor
- **Project demos**: Scheduled in lecture hours in week 10 (online via BB Collab)
  Detailed roster will be announced on the WebCMS3 page of the course

Assessments

Assessment	Marks	Release	Due
Assignment	10%	Week 2	Week 4
Lab Work (4x)	10%	Weeks 2, 3, 4, 5	Weeks 3, 4, 5, 7
Group Project	40%	Week 5	Week 10
Exam	40%	Exam Period	Exam Period

Late submission penalty: Unless you have received special dispensation from the Lecturer in Charge, work submitted after the deadline **during term** will incur a penalty of 5% per day, capped at 5 days, after which submissions are no longer accepted. ***For the final examination, university exam rules apply.***

Communication modes and etiquette

- **Online forum (Ed) is your first port of call** for queries of wider interest on lectures, assignment, labs, project, and assessments
- **Contact the LIC** for late submission, absence, assessment deadlines, and specific questions about the assignment, labs, project, and assessment contents
- **Contact the course admin** for issues with enrolment, file submission, group enrolment, or other administration related matters
- **Team is committed to respond quickly** to queries with a maximum turnaround of 24 hours
- **Do observe standards of equity and respect** in dealing with all students and staff, in person, emails, forum posts, and all other communication
- **Language of communication is English**

Special Consideration

- If your work in this course is affected by unforeseen adverse circumstances, you should **apply for Special Consideration via the UNSW website**
- UNSW handles Special Consideration requests centrally, so **use the website and do not email the Lecturer in Charge about Special Consideration requests**
- Special Consideration **requests must be accompanied by documentation**
- **Marks are calculated the same way** as other students who sat the original assessment
- If you are awarded a Supplementary Exam and do not attend, your exam mark will be zero

See the course webpage on WebCMS3 for more detailed information and links

Plagiarism Policy

READ the UNSW Policy and Procedure on this (links in the course outline on WebCMS3)

For the purposes of COMP9517, plagiarism includes copying or obtaining all, or a substantial part, of the material for your assignment, whether written or graphical report material, or software code, **without written acknowledgement** in your assignment from:

- A location on the internet (including ChatGPT, GitHub Copilot, Google Bard etc.)
- A book, article or other written document (published or unpublished) in any form
- Another student, whether in your class or another class, at UNSW or elsewhere
- Someone else (for example someone who writes assignments for money)

Plagiarism Policy

- If you copy material from another student or non-student **with acknowledgement**, you will not be penalized for plagiarism, but the marks you get for this will be **at the marker's discretion** and will reflect the marker's perception of the amount of work you put into finding and/or adapting the code/text
- If you use text found in a publication (on the internet or elsewhere), the marks you get for this will be **at the marker's discretion** and will reflect the marker's perception of the amount of work you put into finding and/or adapting the text

Assessments provide opportunities for you to develop important skills

Use these opportunities

Copyright Notice

- All course materials made available to you are copyrighted by UNSW
- Reproducing, publishing, posting, distributing, or translating is a copyright infringement
- Infringements will be reported to UNSW Student Conduct and Integrity for action

Further information on WebCMS

Please be sure you are familiar with:

- Communication Etiquette
- Special Consideration
- Student Conduct
- Plagiarism Policy
- Academic Integrity

Further reading on discussed topics

In the lectures we will be referring to various online resources for further reading:

- Richard Szeliski, Computer Vision: Algorithms and Applications, 2nd Edition, Springer, 2021
- Dana H. Ballard and Christopher M. Brown, Computer Vision, Prentice Hall, 1982
- Ian Goodfellow, Yoshua Bengio, Aaron Courville, Deep Learning, MIT Press, 2016
- David A. Forsyth and Jean Ponce, Computer Vision: A Modern Approach, Prentice Hall, 2011
- Simon J. D. Prince, Computer Vision: Models, Learning and Inference, CUP, 2012

And other books, articles, and resources online or via the UNSW Library

Further reading on discussed topics

- Chapter 1 of Szeliski for a general introduction to computer vision
- Appendix A of Szeliski for a recap of linear algebra and numerical techniques